Why trust a simulation? Models, parameters, and robustness in simulation-infected experiments

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Abstract: Computer simulations are nowadays often directly involved in the generation of experimental results. Given this dependency of experiments on computer simulations, that of simulations on models, and that of the models on free parameters, how do researchers establish trust in their experimental results? Using high energy physics (HEP) as a case study, I will identify three different types of robustness that I call conceptual, methodological, and parametric robustness, and show how they can sanction this trust. However, as I will also show, simulation models in HEP themselves fail to exhibit a type of robustness I call inverse parametric robustness. This combination of robustness and failures thereof is best understood by differentiating different epistemic capacities of simulations and different senses of trust: Trusting simulations in their capacity to facilitate credible experimental results can mean accepting them as means for generating belief in these results, while this need not imply believing the models themselves in their capacity to represent an underlying reality.

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1 Introduction

Computer simulations (CSs) are nowadays often directly involved in the generation of experimental results. This fact has recently been recognised by philosophers for raising a number of epistemological challenges: Simulated data are often treated as equivalent to experimental data, and this requires an analysis as to the appropriateness of such treatments (Morrison, 2015; Massimi and Bhimji, 2015; Parker, 2017). Devising a CS presupposes a whole chain of models that includes manifold successive modifications, from simplifications and approximations to outright artificial constructions (Lenhard, 2007; Winsberg, 1999; Morrison, 2009; Winsberg, 2010; Boge and Zeitnitz, 2020). This introduces sources of potential error from incorrect modelling to malfunctioning hard- and software. Finally, (virtually) every CS makes use of parameters that have to be fixed empirically, and this raises the question of how these parameters influence the epistemic status of corresponding experimental results and the models used to facilitate them (Hasse and Lenhard, 2017; Gueguen, 2019; Ritson and Staley, 2020).

Given this dependency of experiments on CSs, the dependency of CSs on modelling assumptions, and the dependency of the models on parameter-choices, I will here investigate the following question: how do researchers establish trust in their experimental results and what does this tell us about the models used? I will here focus on robustness analysis (RA), characterised as a “method for determining which models make trustworthy predictions” by Weisberg (2006, p. 731), as a key to understanding the prospects and limitations of trusting CSs in the generation of simulation-infected experimental results.

Like Staley (2020), I will use experimental High energy physics (HEP), the study of interactions between material particles in high-energetic collisions, as a case study; for Morrison (2015, p. 287) displays CSs as a conditio sine qua non therein: They are used to estimate the discovery potential of detector components before these are built, define the ‘background’ data to be expected in the absence of phenomena of interest for statistical analyses, or even what signatures of interest might look like. Thus, “simulation plays a significant role in the experimental setting” (Morrison, 2015, p. 288, orig. emph.).

I will argue for a differentiated view, according to which (HEP) researchers justifiably trust their experimental results without having to invest outright belief in the simulation models used to facilitate them. I hence distinguish two senses of trust to be potentially invested in simulation models: trust in their capacity to facilitate credible experimental results, and trust in their capacity to faithfully represent an underlying reality. That these can fall apart in principle should be evident: an experimenter’s skill, say, or a measuring instrument, can be trustworthy in the former sense without even being suitable for the latter. However, simulation models are generally intended as (more or less accurate) representations; so it is a non-trivial observation if they turn out trustworthy in the former but not in the latter sense.

To carefully distinguish between both capacities, I will identify four types of robustness, three
of which concern experimental results: (i) their insensitivity to varying modelling assumptions in the definition of simulation programs used in their generation; (ii) to different uses of CS therein; and (iii) to changes in values of the models’ free parameters.1 The fourth, however, concerns the parameters themselves, namely: (iv) the insensitivity of their values to varying experimental conditions in which the models are used.

Below, I will call (i) conceptual robustness (CR), as it concerns the conceptualization of simulation-targets; (ii) methodological robustness (MR), as it concerns simulation-based methods for extracting experimental information; (iii) parametric robustness (PR), for obvious reasons; and (iv) inverse parametric robustness (IPR), as it concerns the parameters, not the results gained with them.

CR, MR, and (some sense of) PR establish a rather solid basis for HEP researchers to trust their experimental results. In contrast, IPR is doubtful, and this has implications for the models’ epistemic status. As I shall argue, the relevant simulation models are best understood as reliable cognitive instruments, not faithful representations of the goings on in the ‘beam pipes’ of colliders.

The structure is as follows: After a recap of some relevant results from the debate on RA (Sect. 2), the first, ‘analytic’ part (Sect.s 3–5) establishes the four types of robustness and the sense of justification they convey. The second, ‘critical’ part (Sect. 6) then inquires about the epistemic status of the models used in relevant inferences. I also offer an outlook, in the conclusion, on why the results are not only interesting w.r.t. the paper’s main case study but simulation-heavy fields more generally.

2 Robustness analysis: Taking stock and looking ahead

Following Wimsatt (1981), the ‘robustness’ of an experimental or theoretical result means its invariance under changing means of detection. Robustness analysis is the process of “exploring the differences in past means of detection that have had no (or a negligible) effect on the result—and also [...] exploring variations that have made a difference to the result” (Schupbach, 2016, p. 277). RA has been applied to models (e.g. Weisberg, 2006; Weisberg and Reisman, 2008; Lloyd, 2009, 2010; Parker, 2011), experiments (Staley, 2004b, 2020; Schupbach, 2016; Karaca, 2018), and CSs (Muldoon, 2007; Durán and Formanek, 2018; Gueguen, 2019; Lehtinen and Kuorikoski, 2007). In HEP, these issues become entangled, and subjecting models and simulation to RA can in principle serve the goal of inferring something about experimental results or the status of simulation models.

Famously, there has been considerable debate about what RA across models can establish. In response to Levins (1966), Orzack and Sober (1993) had objected that Levins’ discussion made RA look like a method of non-empirical confirmation – something not easily acceptable to most philosophers. Furthermore, there is a long-standing debate on how to assess the diversity of different means detection involved in RA, as well as their independence (see Schupbach, 2016, Sect. 2.1–2.4).

These concerns have been forcefully answered by Schupbach (2016): If a certain result is invariant under changing means of detection, then this successively rules out different explana-

1(i) and (iii) are closely related to what Weisberg (2013, pp. 159 ff.) calls parameter and structural robustness, the salient difference being that I am here interested in simulation-infected experimental results, not model behaviour alone.
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tions of that result’s occurrence thus need not be fully independent, so long as accepting one rules out the other as an explanation. Furthermore, models and empirical procedures can in principle be treated on a par as means of detection, whence the consistency between measurement results and model predictions can contribute to the confirmation of a result by safeguarding against reliance on either modelling- or measurement-errors (Winsberg, 2018a,b). However, this (strong) sense of confirmation is obviously not non-empirical.

Most experimental result are quantitative, and two means of detection never yield the exact same values. Hence, I prefer talk of ‘insensitivity’ rather than invariance, meaning that individual results, subjectable to RA, do not so strongly depend on the individual means for detection that they become statistically inconsistent with one another. Salient experimental results in HEP are evidence for, or observations of, new particles, measurements of, e.g., anomalous production-rates for certain final-state particles, or bounds established on certain quantities of interest. ‘Evidence’ and ‘observation’ are technical terms in this context, meaning a discovery-significance above 2.8 or 5 standard deviations, respectively (Franklin, 2013). Since observations and evidence thus rely on measured excesses of events in specific regions of certain kinematic variables, I will treat all these as measurements. Furthermore, ‘measurements’ are rarely ever direct comparisons between physical quantities, but usually involve complex modelling and theoretical inferences (Morrison, 2009, 2015; Tal, 2012, 2016; Parker, 2017).

In a recent paper, Staley (2020) has argued that such results gain their credibility in part from being associated with a measure of systematic uncertainty, which can be fruitfully viewed as the result of a RA, reflecting the impact of choices in the modelling-assumptions facilitating the inference to the desired result. This is consistent with Karaca’s (2018, p. 7) verdict that robustness “comes in degrees in the sense that its extent indicates the extent of convergence of [...] results obtained through different means of detection.” Hence, a result’s systematic uncertainty may be taken to indicate this degree of convergence, when the different means are different models facilitating the experimental inference.

Staley presupposes what he calls the ‘secure evidence framework’ (Staley, 2014, 2020), according to which an epistemic agent needs to evaluate claim, C, that data x count as evidence for hypothesis H in relation to her epistemic situation K and an induced set of epistemically possible scenarios Ω. Defining the result’s systematic and statistical uncertainty is key to weakening C, which, equivalently, means rendering it independent from potentially erroneous assumptions in Ω. For the narrower context of generating a quantitative experimental result (QER), this means that, if a range of different models of an experiment which yields data x all give rise to results within an interval [λ − δ, λ + δ], then stating the result as quantity Q taking on value \( Q = \lambda \pm \delta \) is secure from being dependent on any errors contained in these models.

Without following suit with all the details of Staley’s framework, I will here embrace the notion that the models used to infer a QER reflect what is initially considered epistemically possible, and that RA can serve the purpose of determining the QER’s systematic uncertainty. However, if \([\lambda - \delta, \lambda + \delta]\) exhausts a significant part of the real line, then it is hardly sensible to speak of the “convergence of results obtained through different means of detection”. According

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2 Cf., however, Stegenga and Menon (2017) for an alternative in terms of conditional probabilistic independence.
3 This will become clearer in Sect. 4.1.
4 In contrast, statistical uncertainty is “a characteristic of the distribution of outputs of a single model of a measurement process” (Staley, 2020, p. 92; emph. added).
to Staley (Staley, 2014, pp. 48 ff.; Staley, 2020, p. 103), the strengthening of the premises of an experimental inference, by carefully ruling out models whose inclusion would lead to a wider spread $\pm \delta$, is key for safeguarding against this. I believe that, in actuality, a combination of RAs can also do the trick. I will take up this issue, which has a close connection to the notion of measurement-accuracy, in Sect. 4.3.

### 3 Conceptual robustness

#### 3.1 The modelling challenge

RA with respect to models and their trustworthiness has traditionally been employed in the context of complex sciences without an encompassing fundamental theory, where different models necessarily rely on strongly simplifying and idealising assumptions. Examples include ecology (Weisberg, 2006; Weisberg and Reisman, 2008), climate science (Lloyd, 2009, 2010; Parker, 2011; Winsberg, 2018a,b), or economy (Lehtinen and Kuorikoski, 2007; Kuorikoski et al., 2010). However, with the electroweak theory and quantum chromodynamics (QCD), jointly called the ‘Standard Model’ (SM), HEP features a rather solid theoretical basis. So whence the need for RA?

In fact, the vastness of decays, the nature of the strong coupling (which allows theoretical computations only for very high energies), and the complexity of the instrumentation required to tackle all these decays together necessitate various models that are ‘phenomenological’ in the sense of not being strongly bound to theory in their construction (Suárez and Cartwright, 2008; Karaca, 2013). CSs in HEP comprise two general kinds of simulation based on these models: Monte Carlo event generators (short: ‘generators’), simulating the physics inside the beam pipe, i.e., the metallic tube in which particles collide; and detector simulations, simulating the interaction of sufficiently stable decay-products with detector-components (ATLAS Collaboration, 2010).

Generators are further divided into several stages, called hard scatter, underlying event, parton shower, and hadronisation. These are heuristically assumed to separate, but feature manifold connections that ultimately impose the need for mutual recalibration (Boge and Zeitnitz, 2020). The hard scatter is the elementary scattering process with the highest momentum transfer in the scattering, an interaction between two constituent partons (quarks or gluons) of the scattering protons. This is usually the process of interest, because here one may expect the production of sought-for particles. The underlying event means additional, less energetic scatterings, or even particles remaining from previous or differently located scatters. The parton shower is the emission of additional gluons by the accelerating and decelerating coloured particles before and after the primary interaction. This may be understood in analogy to the ‘Bremsstrahlung’ of accelerating and decelerating electrical charges, but with the radiated particles (gluons) being coloured and emitting further radiation. Finally, at lower energies, the confining effects of QCD become important, and partons begin to hadronise, i.e., combine into complex particles, most of which subsequently decay into more stable ones.

All this goes on before any interaction with the detector. The LHC-detectors are giant apparatuses comprising various technologies. Accordingly, detector simulation takes inputs also from data, atomic, nuclear, and solid state physics (see GEANT Collaboration, 2016).

Basically all models in this context require extra-theoretic considerations. The hard pro-
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Process builds on perturbative QCD-calculations to some fixed order in a series-development of elementary cross sections. However, proton-proton cross sections are thereby assumed to ‘factorise’ into weighted sums of parton-level cross sections; an assumption is actually only proven for a small range of cases (Schwartz, 2014, p. 685; Collins, 2011, pp. 1–2). The resulting probability-weights (called ‘parton density functions’), furthermore, can only be obtained by fitting parametric functions to a broad range of data (also Staley, 2020; Ritson and Staley, 2020). Similarly, shower models utilize an approximate QCD-result as the basis of a Markov-chain in which partons are radiated at distinct times (cf. Höche, 2016, p. 242). But the resulting probability-functions diverge in the limit where the approximation becomes exact, and CSs include a pragmatic cut-off, corresponding to the resolution of the detector.

Theoretical results are especially sparse for hadronisation, since perturbative QCD breaks down at lower energies. Furthermore, these models “inextricably couple” (Dissertori et al., 2003, p. 172) to other models in the chain, which forestalls validating them independently. Hence the need for RA. However, for an RA to even possibly succeed, different models of the same process need build on different idealising and simplifying assumptions, so that RA can exclude a common result to be an artefact of any particular set of such assumptions. Focussing on hadronisation as the weakest link in the simulation-chain, and ‘string’ and ‘cluster’ models as the currently most common ones, I shall briefly expand on this.

The main differences here reside in the treatment of the color field. String models focus on a particular limiting behaviour of this field and largely ignore its quantum nature. They model it as a flexible string, binding pair-produced quarks, with dynamics determined by a parametric ‘fragmentation function’ that specifies under which conditions the string tears. This event indicates the creation of two (unstable) mesons, corresponding to the string fragments.

In contrast, cluster models focus on certain quantum aspects, namely the prediction of color-entanglement between neighbouring quarks, also called ‘preconfinement’ into ‘clusters’, from a QCD-approximation which formally takes the number of colour charges to infinity. The resulting clusters can be shown to follow a universal (not decay-specific) mass-distribution, which the simulation samples. Thus, cluster models completely neglect the field-dynamics.

Similarly, whereas cluster models split gluons from the shower stage non-perturbatively into quark-anti quark pairs, and so essentially ignore them, string models at least preserve them as an aspect of the semi-classical, string-like field: as ‘kinks’ (or transverse excitations) in the string, which leads to the generic prediction of a more frequent occurrence of hadrons between quark and gluon.

3.2 Never trust a (single) generator!

Given these preliminaries, the case for CR is straightforward, and has in part been covered by Staley (2020, p. 110). Physicists have various generators at their disposal, and comparing the results gathered from using different generators is basically mandatory:

Monte Carlo event generators are complicated programs that will almost inevitably contain bugs, incorrect assumptions and ill-chosen parameters. It is therefore vital that a user does not take any results at face value. As a minimum at least two

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5This is similarly true of underlying event or detector models; but the modelling-freedom in the former is constrained by the similarity to the hard scatter, and the latter can in part be validated directly (Boge and Zeitnitz, 2020, pp. 28–9).
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completely independent programs should be used in any physics study. (Dissertori et al., 2003, p. 204; emph. omitted)

A number of things are worth emphasising though. First, the mention of “completely independent programs” is well in line with Levins’ famous slogan that the “truth” established by RA is “the intersection of independent lies” (Levins, 1966, 423). However, there are various connections between different hadronisation models and programs, and so talk of complete independence is far-fetched. As explained in Sect. 2, this need not pose a problem, so long as RA across different models can rule out the explanation of a certain result as an artefact of the idealising and simplifying properties of these models.

Second, establishing this sort of CR is piecemeal work, and an RA across models needs to be performed for every data-model-combination. A recent study on the top quark-mass, for example, employed a newer set of (‘special-purpose’) generators, capable of computing next-to-leading order matrix elements. But the results varied grossly when these were interfaced with two different ‘general-purpose’ generators—“to the point of drastically altering the conclusions” (Ravasio et al., 2018, p. 3). Hence, depending on the data-model-combination, CR may fail.

Third, the differences in simulation results, due especially to the limited understanding of the hadronisation phase, are generally used to define a “hadronization uncertainty” (Dissertori et al., 2003, p. 244; emph. omitted), in perfect agreement with Staley’s assessment. Similarly, “in order to assess a meaningful theoretical error […] the use of different shower models[…] is mandatory.” (Ravasio et al., 2018, p. 4; emph. added)

However, this is considered a “pragmatic approach to assessing the uncertainties associated with hadronization” (Dissertori et al., 2003, 172; emphasis added), or simulation more generally. There is, in other words, no solid a priori reason for determining uncertainty in this or any other way. In addition, one frequently finds that the prescription uttered by Dissertori et al. is obeyed only in a minimal sense, i.e., that only two sets of generators are used for robustness-checks. Besides such concerns as computational expensiveness, this reliance on a minimal number of different models may be rooted in the vastness of the differences between them.6

Concluding that a common result is unlikely to arise coincidentally from two very different models is well in line with the general thinking underpinning RA (e.g. Kuorikoski et al., 2010, p. 544); albeit with the unlikely coincidental nature of the result rooted in the vastness of differences rather than the number of models. Still, it is not clear just how safe an experimental conclusion relying on a limited number of models like this really is.

4 Methodological robustness

4.1 Convergence of results

Given the aforementioned restrictions in relying on CR alone, it is understandable that this is not the only sort of RA physicists in HEP perform. To see this, consider the different measurements of the top quark mass, $m_t$, displayed in Fig. 1. Neither do the central values of $m_t$ coincide, nor

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6 For example, Herwig not only uses cluster- rather than string-hadronisation, but also an angular ordering in the parton shower rather than the momentum ordering of Pythia (Bähr et al., 2008; Sjöstrand et al., 2008). This means slicing the radiation process in different ways, and is but one of many theoretically allowed choices.
do all margins of total uncertainty overlap. But most of them do, and they all overlap with the uncertainty of the combined world average. In the sense of an overlap to within uncertainty, all these different measurements are hence consistent with the central claim that $m_t = 173.34 \pm 0.76$ GeV.

To infer these different values, ATLAS and CMS used several decay channels, as specified by comments like ‘ℓ(pton) + jets’ or ‘single top’. This means that, next to the fact that several generators are used in each individual measurement, there are also different processes simulated each time. Furthermore, the standard tool for simulating detector effects, the GEANT simulation tool-kit, comprises a vast range of detailed physics models (see GEANT Collaboration, 2016), and interactions vary with decay chains—as do materials and geometry between ATLAS and CMS (cf. Seiden, 2012). Finally, the combined world average also contains results from the D0 and CDF collaborations at Fermilab, which used protons and anti-protons, scattered at much lower energies, with final-state products measured by yet other detectors (see ATLAS, CDF, CMS and D0 Collaborations, 2014).

### Figure 1: Summary of measurements of $m_t$ by the LHC top working group (© CERN 2019).

Additionally, another sort of variation is performed across several measurements: Two standard analyses are the template and matrix element method, and the roles played by simulated data differ crucially across these and further analyses. In the first, a range of input values for $m_t$ are used to generate simulated histograms. These are then used as ‘templates’ for what actual data should look like, given a value of $m_t$, and one infers the best value by means of likelihood maximisation (see ATLAS Collaboration, 2012). Hence, simulated data are used in a direct, positive fashion in the template method.

In the matrix element method, one instead calculates from the theory as far as possible, using different values of $m_t$, and predicts the states to be measured after interaction with the detector.
from a parametric ‘response function’. This function also subsumes shower and hadronisation effects, thus bypassing a direct involvement of relevant models (Fiedler et al., 2010, p. 204–5). The parameters of that function are, however, usually fixed using simulated data (D0 Collaboration, 2006), and so CSs still enter indirectly. They also enter negatively in defining the distribution of events to be expected on the ‘background only’-hypothesis (Fiedler et al., 2010, p. 212).

4.2 Discrimination

Given all these differences, the consistency between the different results is certainly remarkable. However, by itself, this does not yet rule out that the convergence is due to dependencies between the different usages of CSs. It seems clear that neither usage of CSs is fully independent of the other; for instance, they do not seem to satisfy ‘ontic independence’ (Stegenga and Menon, 2017, p. 414), i.e., that “the multiple lines of evidence depend on different materials, assumptions, or theories”. But are they ‘independent enough’ to ensure that MR is not a kind of ‘pseudo-robustness’ (Staley, 2004b, p. 473; Karaca, 2018, p. 4)?

In order to safeguard against this possibility, different measurements, making use of CSs in different ways, should not be “correlated with each other to the extent that they yield convergent results when they should not” (Karaca, 2018, p. 2). Both Staley (2004b) and Karaca (2018) consider the case of different $b$-tagging algorithms, which were compared as to their ‘mistags’ in the top-quark discovery. Since these differed among different algorithms, the algorithms were not simply ‘correlated all across the board’. However, in establishing MR, CSs are used to simulate different things, whence this sort of “discriminant validation” (Campbell and Fiske, 1959, p. 81) is not feasible.

Another, encompassing sense of discrimination is captured by Schupbach (2016, p. 293 ff.), who considers several detections $R_1, R_2, \ldots, R_{n-1}$, so far compatible with hypotheses $H$ and $H'$, where $H'$ signifies the hoped-for explanation of the apparently robust result, and $H$ is any rival explanation. $H$ and $H'$ could in principle logically coexist, but accepting $H'$ implies that $H$ becomes a bad explanation for the past detections. Discrimination now means that, relative to the remaining $n - 1$ detections, detection $R_n$ can really only be explained by $H'$, not $H$. This is an iterative process: each of the $n$ detections may rule out a different hypothesis $H$, so as to only leave $H'$ as a plausible explanation.

For robustness to be more than just apparent, different detections themselves hence need to discriminate against different hypotheses $H$, i.e., against explanations of the convergent result in terms of artefacts introduced by either detection. So to rule out, e.g., that the result is purely due to $b$-tagging algorithms’ spurious general agreement, one could instead also check these measurements’ consistency with measurements without $b$-tagging.

In the case of the different usages of CSs, the different hypotheses $H$ ruled out are that the measurement result is influenced by the given CS to the extent of becoming an artefact. In contrast, the hypothesis $H'$ to be inferred in case of success is the central result that is consistent with all the individual measurements (here: $m_t = 173.34 \pm 0.76$ GeV). $H$ and $H'$ are logically compatible: The actual value might simply happen to lie in the inferred interval even if individual measurements predict this on the basis of simulation-related artefacts.

That the different detections of $m_t$ are indeed relevantly discriminating can be seen as follows: Simulating only the background, as in the matrix element method, means eliminating the
possibility that the value $m_t = 173.34 \pm 0.76 \text{ GeV}$ is inferred purely due to a misidentification of the signal-shape on the basis of modelling errors (as might happen in the template method). Similarly, inferring values consistent with $H'$ both from templates which contain a single lepton and templates which contain only hadronic jets means ruling out that the result is inferred purely due to a misidentification of the properties of the lepton. The $\ell+\text{jets}$ and all jets-channels also do not depend equally strongly on the choice of hadronisation model, and the corresponding uncertainties derived by CMS differ by 350 MeV (ATLAS, CDF, CMS and D0 Collaborations, 2014, p. 20). (And so forth.) Hence, the aforementioned differences render pseudo-robustness at least very improbable.

### 4.3 Security versus informativeness

Recall now how a quantitative RA can only succeed if results from different detections lie in sufficient proximity. In close connection to this observation, Parker (2017, p. 279; emph. added) points out that “a well-motivated uncertainty estimate [...] also indicates the degree to which the measuring process is expected to be informative”, where by “informativeness”, she roughly means the extent to which a result narrows down the epistemic background possibilities an agent can coherently entertain. Similarly, Staley (2020, pp. 105–6) concerns himself with a measurement’s sensitivity to the phenomena of interest, construed as “the ability of a measurement result to inform our answers to substantive physics questions.”

Thus, there appear to be two distinct pay-offs to a quantitative RA: (A) Securing the result from being severely wrong by quantifying the impact of possible errors in its generation; and (B) establishing its informativeness by exhibiting the extent to which individual detections converge. However, (A) and (B) pull in opposite directions: A broader uncertainty margin is ‘safer’, as it admits to more potential errors; but it arguably renders the result less informative.

Another way of phrasing things is in terms of accuracy. Following Tal (2012, pp. 30–2), there are several different readings of ‘measurement-accuracy’, and construed epistemically, ‘accuracy’ means that the design and use of an instrument or procedure “warrant the attribution of a narrow range of [...] values to objects” under study (ibid, p. 31). This is not to be conflated with precision, which is just one aspect of epistemic accuracy, with imprecision being “caused by uncontrolled variations to the equipment, operation or environment when measurements are repeated” (ibid, p. 32). In contrast, uncertainty, construed as an antonym to epistemic accuracy, can obviously also have systematic sources (ibid.). Furthermore, ‘accuracy’ can also be meant in a comparative sense, i.e., as a result’s reproducibility “under controlled variations to measurement conditions and methods.” (ibid.)

However, epistemic accuracy thus also delivers a (though not ‘the’) measure of a QER’s informativeness: A QER with small uncertainty is not only epistemically accurate, but also informative about the phenomena of interest, since it rules out a broader spectrum of models or theories. If a QER yields $\hat{Q} \in \Delta$, but theory $T$ predicts that quantity $Q$ actually has a value in $\Gamma$, where $\Gamma \cap \Delta = \emptyset$, $T$ may stand refuted unless one finds reasons to broaden the uncertainty margin (e.g. by reassessing the auxiliary hypotheses needed to derive $Q \in \Gamma$ from $T$).

As mentioned before, Staley (2020, Sect. 7) addresses these issues in terms of ‘strengthening strategies’ that (mostly) consist in ruling out possibly erroneous premises empirically, thereby

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7Following Beauchemin (2017), he means by ‘sensitivity’ that the result’s uncertainty is small enough to discriminate between different theoretical predictions (see Staley, 2020, p. 106). It is easily seen that this closely corresponds to the notion of informativeness I invoke below.
decreasing the uncertainty margin. However, this too is not generally feasible for HEP sim-
ulation models, due to their ‘inextricable coupling’. Luckily, physicists have another ace up
their sleeves. To see this, consider $m_t$’s combined world average again, which was computed
by the ATLAS, CDF, CMS and D0 Collaborations (2014) using an algorithm that approximates
the best linear unbiased estimate (‘BLUE’); that linear combination of the different measured
values which minimises overall uncertainty. Hence, the resulting uncertainty-measure specifies
the minimum uncertainty that has to be assumed when all measurements are taken into account.
This uncertainty is larger than that of the overall ATLAS and CMS values, but smaller than
that of their combined value. It is also smaller than that of more than 80% of the results from
individual decay-chains. Hence, by replacing the epistemic accuracies associated with the indi-
vidual results by a comparative measure of accuracy that establishes their consistency to within
a rather narrow span, the combined result is not only more secure but also more informative
than most individual results. In other words: by directly determining the extent of convergence
between individual results, physicists achieve a balance between security and informativeness
from a skilful combination of RAs, without the need to appeal to external strengthening strat-
egies.

5 Robustness and parameters

5.1 Universal or not?

CSs in HEP depend on a whole number of free parameters, and such an occurrence of parame-
ters is ubiquitous in simulation-intensive sciences, but “has received surprisingly little attention
from philosophers.” (Hasse and Lenhard, 2017, p. 95) Free parameters bear the danger of spoil-
ing predictivity: The success that string models can claim by predicting a specific distribution of
hadrons from kinks in the string is arguably undermined by the fact that these predictions only
obtain a quantitatively precise form once the model’s parameters have been fitted to data. Given
that successful predictions are the hallmark of confirmation, this means trouble for parametrised
models.

Of course, parameters are actually ubiquitous in science overall: With neutrino masses, the
SM itself has 27 free parameters, but this has not hindered its being hailed the most successful
scientific theory to date. Three factors have arguably facilitated this immunity to the parameters’
success-undermining power: (a) They are physically meaningful quantities (such as masses and
couplings); (b) there are certain dependencies between them that constrain some of them, once
some others have been fixed (they exhibit an exploitable coherence); and, most importantly, (c)
“the Standard Model is an overconstrained system – we can test it by making enough measure-
ments with enough precision.” (Schwartz, 2014, p. 641)

When literally thought of as parameters of a model, (c) expresses the property I have called
inverse parametric robustness (IPR) in Sect. 1: There is a set of values that can be consistently
inferred from a range of rather different experimental settings. However, on account of (a), these
‘parameters’ of the SM are simply experimentally robust quantities in the traditional sense (e.g.

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8I admit that the increase in informativeness is accompanied by a decrease in security at the level of meta-analysis:
In using the BLUE-method, certain non-trivial assumptions have to be made, such as results being Gaussian-
distributed. However, the general epistemic intuition, that the best value must lie somewhere in between and
should be associated with the minimum uncertainty necessitated by all results, would certainly be served by
many other methods.
Staley, 2004b; Schupbach, 2016; Karaca, 2018).

Now, are (a)–(c) also true of the parameters that occur in HEP simulation models? Let us address this step by step. First of all, one of the two fundamental string parameters was initially used to model a ‘string tension’, or rather, the uniform energy-density of the narrow flux-tube into which the colour-field is supposed to collapse on account of the model. This idea gained momentum from an analogy to an approximate result from quantum electrodynamics, but the approximation is known to be poor, and predictions based on the physically suggested value for the parameter are often off by large percentages (see, e.g. Dissertori et al., 2003, p. 166).

This type of process is characteristic of HEP simulation parameters. So by and large, the situation appears to be as in thermodynamics, where certain “models have parameters which describe physical quantities in the simple context for which they were initially developed. [...] But in the complex context in which they are used as fitting parameters, the original physical meaning is lost[...].” (Hasse and Lenhard, 2017, p. 109)

So much for (a). What about (b), the parameters’ exploitable coherence? As emphasized already in Sect. 3.1, HEP simulation parameters are “closely entangled” (Corcella et al., 2018, p. 489), so it is in general not feasible to fix some of them first and then use these to constrain others. Hence, neither (a) nor (b) seem to hold for HEP simulation parameters.

It could be argued, though, that this is not so bad, so long as parameters can at least be fixed once and for all: (b) seems mostly like a convenience, and the failure of (a) mostly says that these parameters do not have a fundamental meaning. But they might still offer a phenomenological (i.e.: coarse, non-fundamental) representation of the physics inside particle colliders.

In this connection, it is important to note the generic split between event generators and detector simulations. While it is in principle conceivable that the detector exerts a non-negligible influence, the modelling proceeds as if the physics inside the beam pipe fully decouples from what goes on inside the detector. Hence, to establish a phenomenological pendant of (a), it would at least be necessary to establish a uniquely best set of parameters across the different experiments at the LHC, where scattered particles and energies are identical.

In fact, there are even stronger allusions to the universality of certain parameter-values in the physics literature:

one finds in practice that [...] a single set of parameters describes the data at a wide range of energies and processes. [...] Thus, hadronization models tuned to $e^+e^-$ annihilation, and lower energy hadron collider data, are highly predictive for LHC events. (Seymour and Marx, 2015, pp. 309–10)

The “in practice” and the “wide range of energies and processes” here indicate that, insofar as universality can be established, it is partially grounded in RA. More precisely, parameters are initially ‘tuned’ or calibrated to certain reference-data that can be understood without the simulation. This can be done in a variety of ways, for instance by manually adjusting them in direct comparison with data, or by randomly sampling from a large number of choices until an optimum value is reached, as determined by a goodness-of-fit metric. More systematic approaches, such as the Professor-toolkit (Buckley et al., 2010), optimize polynomial expansions of the Monte Carlo predictions in several orders of their parameters across large numbers of bin-values for various observables.

Because of the appeal to reference-data, ‘tuning’ means establishing a given choice of values experimentally, but in a way that might still depend on the peculiarities of the chosen data. The
established parameter-set is hence usually validated on further data. This is done, for instance, using the \texttt{Rivet}-toolkit (Bierlich et al., 2020), “a library of experimental analyses and of tools for calculating physical observables from an event record” (Buckley et al., 2010, p. 332). Since each validation means testing whether the parameter-set describes the relevant data reasonably well, a set of values that achieves a good fit across these varying experimental conditions can be called ‘robust’ in the sense of IPR.

Now I said that claims to universality are \textit{partially} grounded in an experimental RA, and the reason is that it is also theory-supported:

One can show that this is a consequence of preconfinement: the perturbative production and evolution of partons takes care of the process and energy-dependence and the transition from partons to hadrons is a local process, independent of these factors. (Seymour and Marx, 2015, p. 310)

However, recall that preconfinement is only an approximate result, derived by taking the number of colour-charges to infinity. There are, in fact, also theoretical reasons for \textit{doubting} IPR:

\begin{itemize}
  \item it is not absolutely guaranteed that models which reproduce $e^+e^-$ data work equally well in a colored environment like $\bar{t}t$ events at the LHC, where initial-state radiation, color reconnection and underlying event play a role. (Corcella, 2019, p. 71)
  \item This is not an academic point: The ‘Monash tuning’ for \texttt{Pythia} (Skands et al., 2014), for instance, which mostly exploited LHC-data rather than data from electron-positron-scattering, led to significant changes in certain string parameters (with some parameters being more than \textit{doubled}; cf. Skands et al., 2014, Tab. 4), and simultaneously to improvements in correspondence with several data. Skands et al. (2014, p. 1) also mention some “interesting discrepancies” though, as well as several generic reasons for further improving the \texttt{Pythia}-code, which “should in principle be accompanied by a reevaluation of the model constraints.” (Skands et al., 2014, p. 27) Accordingly, the tune is “[b]y no means […] the final word”, and the study gives a bold outlook on the difficulties associated with IPR:
    \begin{itemize}
      \item If[…] some data sets result in significantly different tune parameters, one has a powerful indication that the universality of the underlying modeling is breaking down […]. (Skands et al., 2014, p. 31)
    \end{itemize}
  \item Still, differences between the Monash tune and the former default are accompanied by important physical differences: In the default tune, the scatterers were leptonic (and so not coloured), whence, for instance, no initial-state gluon radiation is to be expected. Hence, the above verdict could still be upheld at this point: So long as there was a uniquely best tune across different LHC experiments, where the phenomenology is the same, these parameters could have physical meaning.
  \item This is far from true though: \textit{each} LHC-collaboration, like ATLAS or CMS, has a \textit{whole range} of different tunes for the same generator, depending on the details of use. An impressive – though far from exhaustive – overview can be gathered from websites and documentation files for different generators.\textsuperscript{9}
\end{itemize}

\textsuperscript{9}E.g. http://home.thep.lu.se/~torbjorn/pythia82html/Tunes.html (checked 01/21).
To get an impression of the purpose-dependency, it is instructive to consider the four different tunes devised by the Atlas Collaboration (2014) to match underlying event-data. When combined with one out of four parton density functions specified in the study, each of these achieved a good fit to reference data; but they vary amongst each other by up to some 24% of the lowest value of some parameters, and there is also a mention of “[a]dditional tunes [...] in preparation for use with higher-order matrix elements.” (ibid., p. 1)

Given the relatively big differences in these values, even for one specific purpose, the possibility of associating a definite phenomenological meaning to these parameters seems pretty much spoiled. There is, in other words, no solid ground for claiming IPR to hold across the LHC.

5.2 Tuning for accuracy

The apparent failure of IPR clearly impacts the models’ representational capacity: If their parameters were to describe physical properties of processes like hadronisation or the parton shower, their values should not be sensitive to the detector used, or to the specific type of event simulated. Even more so, there should not be several different, but equally suitable, values for the exact same simulated event. However, does this failure of IPR also spoil the possibility of trusting these models in their QER-facilitating capacity?

To address this question, observe, e.g., that the greatest differences effected in measurable quantities by the Monash tuning were in the order of 10% (Skands et al., 2014, p. 29). This is certainly not nothing, but also a big stretch from doubling, or even 24%. Furthermore, large uncertainties in parameters certainly can influence experimental results: In the 1990s, Tevatron-data were interpreted as indicating evidence for a new level of sub-quark particles—which evidence vanished when parton density functions were recalibrated on additional data (Dorigo, 2016, Chapt. 9). However, uncertainty propagation often results in only small contributions to quantities of interest, which safeguards against such an effect. Hence, even if IPR fails, isn’t PR, the insensitivity of results to changes in parameter-values, enough to render at least simulation-infected experimental results trustworthy?

I believe this is ultimately correct, but given the failure of IPR, PR itself enjoys a subtle status in HEP. To see this in detail, consider a recent study (Corcella et al., 2018) of the sensitivity of \(m_t\)-measurements to simulation-parameters. Since \(m_t\) is pivotal for constraining the Higgs-mass or determining the life-time of the SM-vacuum, it is “of paramount importance to measure \(m_t\) with the highest possible accuracy” (ibid., p 486).

A central problem in \(m_t\)’s determination resides in fundamental uncertainties in the energy-scale of \(b\)-jets; characteristically broad jets of hadronic particles resulting from decays of heavy \(b\)-quarks, intermediate in top-decays. An alternative is to exploit decays in which the \(b\)-quark forms a \(B\)-meson, a \(b\)-flavoured hadron which then decays into other characteristic particles. In this case, jet uncertainties do not enter in the same ways, but:

a crucial role is nevertheless played by the hadronization of \(b\) quarks into \(B\)-hadrons and the associated Monte Carlo uncertainty. (Corcella et al., 2018, p. 487)

In order to determine the impact of changes in the hadronisation parameters, Corcella et al. (2018) performed a sensitivity-analysis for relevant measurements. Surprisingly, \(m_t\) was most sensitive to the strong coupling for final state radiation in Pythia’s (partly theory-driven) parton
shower, not to any of the (essentially free) hadronisation parameters (see Table 7 in Corcella et al., 2018). Moreover, when inferred from certain dedicated observables, the sensitivity of \( m_t \) to simulation parameters turned out to be comparatively low overall.

*Prima facie*, the study delivers a solid reason to think that experimental results can be robust against changes in the simulation-parameters when the observables used to infer them are carefully chosen. However, there are several curious features contained in the reasoning expressed therein. First off, Corcella et al. (2018, p. 492) avoided “values too far from the default” and varied parameters “up and down by at most 20% of their central values.” By itself, the restriction to a certain range of variation is nothing worrisome, and neither is, necessarily, the restriction to 20%: standards of variation in estimating uncertainty are generally fixed by convention in HEP.

What is peculiar is the *reason* given by Corcella et al. (2018, ibid.; emph. added) for restricting attention to 20% rather than, say, 50%; namely, that “values too far from the default [...] might generate unforeseen changes in the Monte Carlo predictions”. The philosopher well educated in the pitfalls of reasoning should be struck by this comment. For wasn’t the very reason for performing a sensitivity analysis to determine whether changes in the parameters *do* lead to unforeseen changes in predictions? Taken literally, this quote hence expresses a *petitio*: If the possibility of “unforeseen changes” was used to justify confining one’s attention to ranges where these are *not* expected, the expectation of a small impact of parameter variations would follow trivially. This cannot be right.

Now IPR could establish a rational reason for confining attention to the particular region. I.e., if, given all empirical evidence, it was safe to assume that the parameters must lie in close proximity to one particular tune, varying them by only a small percentage would be justified. However, we already know that this is not true. The actual reasons for the 20%-restriction were rooted rather in the fact that the analysis was (largely) based on the Monash tune, which, to recall, was itself based on LHC data. Hence, *specificity to the experimental context* grounded the restriction to a preferred region of values, not robustness across various experimental contexts.

This sort of specificity is driven on the edge by the eventual method for increasing accuracy suggested by Corcella et al. (2018): An *in situ* calibration of simulation-parameters, by defining a number of ‘calibration observables’ relevant to the general measurement of \( m_t \), but rather insensitive to \( m_t \) itself, and tuning the simulation directly to \( m_t \)-data. Notably, *circularity* is evaded if calibration observables are chosen such that they do not (strongly) depend on \( m_t \).

But: “it will be very unlikely for such fits to be ‘universal’, i.e., they are not expected to be reliable outside the *very* same data sample accounted for in the parameter adjustment.” (Corcella et al., 2018, p. 520; emphasis original)

The point to be gathered is this: A high amount of PR can only be established by first calibrating parameters in a highly specific way – maybe even to one particular decay-chain. This does not speak against PR’s relevance for establishing trust in the CSs’ result-facilitating capacity *per se*. But it forcefully underscores that it seems rather impossible to associate their parameters with a definite physical meaning, and raises the question of how else to understand these.

There is another sense in which PR can be established: In the global analysis discussed in Sect. 4.1, different studies also used different tunes. Hence, next to MR, this analysis also brings home some amount of PR, by establishing a consistent result from several tunes. By itself,
however, this ability to infer consistent results from different parameter-tunings is insufficient for securing results from error as well. An impressive example from astrophysics is discussed by Gueguen (2019), where several CSs converge on a prediction for the disruption of dark matter subhaloes for a certain choice of parameters—“[b]ut if another region of the parameter space is scrutinized, convergence is found on another prediction, that contradicts the former.” (ibid., p. 9) Hence, at least one of these convergences must be spurious, produced as an artefact of the tuning.

I believe that physicists in HEP are in a better position, for two reasons. First, in the generation of QERs in HEP, such as that of the world average for \( m_t \), several distinct tunings are used to generate consistent results; not just one tuning per CS, as in the astrophysics case. Second, given that HEP is experimental rather than observational, in the sense that researchers enjoy a high degree of control over their objects of study, these tunings can be validated against reference data. Obviously, this is only possible if the given tuning is not entirely specific to the experimental context in which it is ultimately used, i.e., not generated in situ. Nevertheless the consistency between results inferred by appeal to highly specific tunes and well-validated, less specific ones gives HEP physicists an edge in claims to PR.

6 Trust and its limits

6.1 Commonality, confirmation, and two senses of trust

Overall, CR, MR, and PR together secure a rather solid basis for investing belief in experimental results, in the sense that they are probably not artefacts, and that future developments in theory, experiment, and modelling will not lead to radical changes in their central values. However, what, if anything, can and do these RAs establish about the models themselves?

Recall that a key role in RAs across models is played not only by the differences in idealisation and simplification, but also by what is common to all models (Weisberg, 2006; Schupbach, 2016). The commonalities between string and cluster models, e.g., mostly reside in qualitative features of QCD, such as pair-creation out of the vacuum, (pre-)confinement to intermediate, short-lived hadrons (‘strings’, ‘clusters’, etc.), and energy-momentum-conservation in the non-perturbative regime. Given that there are many shared predictions between these models, those features could give rise to robust theorems (Levins, 1966; Weisberg, 2006; Weisberg and Reisman, 2008). A now-classic example is the ‘Volterra property’ (Weisberg, 2006; Weisberg and Reisman, 2008): that a general biocide increases the abundance of prey and decreases the abundance of predators. The common structure of ecological models predicting this is a negative coupling between prey and predators, i.e., that more prey leads to more predators but more predators lead to less prey (ibid., p. 114). Hence, it is a robust theorem that (ceteris paribus) a predator-prey system with this sort of coupling will exhibit the Volterra property.

The existence of robust theorems paves the way to what Weisberg (2006, p. 740; emph. omitted) calls “low-level confirmation”: that “certain mathematical structures can adequately represent properties of target phenomena.” This is to be distinguished from the much stronger sense of confirmation gained by inferring a result consistently from various models and empirical data in concert. However, robust theorems are of the conditional form ‘If structure \( S \) is present, then, ceteris paribus, property \( P \) will be instantiated’, so low-level confirmation could be conceived of semi-empirically, as an induction over antecedent hypotheses: All models con-
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consistent with evidence so far (i.e., that exhibited $P$) had certain antecedent-properties ($S$); hence, probably any model will. In turn, this may single out the uniquely best modelling assumptions, pointing to an underlying reality.

This is a sensible account of confirmation directly from a model-based RA, compatible also with considerations by Lloyd (2010). A general reason for scepticism is that it is never really possible to tell how much of the hypothesis-space has been exhausted (Stanford, 2006; van Fraassen, 1989). However, there are far more specific reasons to be sceptical in this particular context, covered in Sect. 6.3. For now, note that what could possibly be confirmed here are very generic features of QCD, already assumed to be correct by the physics community. Hence, these robust theorems are not particularly interesting.

Non-empirical confirmation has received a new spin from the debate on theories in fundamental physics (Dawid, 2013; Dardashti et al., 2019), and some authors in that debate (e.g. Smeenk, 2019; Cabrera, 2018) distinguish between two senses of trust one can invest in a theoretical entity: trust in the sense of belief, and trust in the sense of acceptance, where in contrast to belief, “acceptance is context-dependent, shaped by factors other than evidence, voluntary, and exempt from demands for overall consistency across contexts.” (Frost-Arnold, 2014, 1964)

Trusting HEP simulation models in their capacity to facilitate experimental results could mean accepting them in the voluntary, context-dependent sense indicated by Frost-Arnold (2014). However, this does not imply a commitment to accepting them as candidate representations of the goings on in the beam pipe. Hence, it also does not settle the question as to ‘as what’ we may accept them.

6.2 Instrumental reliability

Observe, now, that part of the reason why PR is possible lies in the availability of various tunings. In other words: The very feature that makes these CSs suspicious as candidate representations of the goings on in the beam pipe promotes their trustworthiness in their QER-facilitating capacity. I now turn to a positive account of ‘as what’ we should accept these simulation models that takes this observation to heart. In this connection, note another important observation by Hasse and Lenhard (2017, p. 102):

Calibration [...] is used in the context of measuring instruments. Hence, [...] calibration of parameters makes models look a bit like precision instruments.

While Hasse and Lenhard themselves do not endorse this reading, I believe it is right on track: The delicate status of parameters exhibited above leaves us in no better position than to regard HEP simulation models as reliable (cognitive) instruments, insofar as they establish an inferential connection between data and QERs without painting a trustworthy picture of the underlying reality.11

To see this more clearly, consider Tal’s (2012, pp. 151 ff.) elaborate account of what he calls ‘white box’-calibration. What is ‘white boxed’ here is the overall model of the experiment to which a given instrument is calibrated.12 This models includes several parameters, representing

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11 I do not mean this instrumentalism in any overly restrictive sense, i.e., do not commit “the mistake of imagining that a theory [or model] is simply a tool for moving inferentially from some states of affairs [...] to others” (Stanford, 2006, p. 207; orig. emph.).

12 It is important not to conflate several issues here: Tal (2012) cites Boumans (2006), who applies ‘white box’ to models that are sufficiently transparent to answer why-questions. But a simulation model can, of course,
the properties of the instrument itself, details about the reference data to calibrate on, the impact of background effects, etc. For an instrument indication to be informative about the value of the quantity to be measured, a ‘calibration function’ must be established which delivers the instrument indications as a function of the quantity’s values, relative to the parameters of the white box-model. In a final step, a ‘backward function’ is then established, which allows to infer values from instrument indications relative to these parameters.

A subset of the parameters directly characterize the instrument. For instance, in the specification of properties of a calliper (cf. Tal, 2012, p. 152), some, like the fineness of the scale or the length of the leg, can be considered as intrinsic to it. The remaining parameters will characterize ambient features such as properties of the reference data, experimental conditions, etc. Some parameters will also represent – often indirectly – a relation between instrument and ambient conditions, like the temperature of the calliper-scale, which indirectly characterizes the energy-exchange with the environment (cf. Tal, 2012, p. 153).

Now in the calliper models, as discussed by Tal, all these properties are considered fixed. However, some instruments’ properties are flexible, and this allows adjusting the instrument to the given experimental context. For example, an ordinary pressure gauge has mechanical connections and adjustable links that can be unscrewed and repositioned, and this may be necessary depending on the ambient environmental conditions (Cable, 2005, pp. 52–5). Tweaking the instrument-properties in this way is formally analogous to fitting the calibration function by adjusting some of its parameters. But fitting the parameters of a simulation model may thus be viewed as adjusting an instrument’s properties to ambient conditions of use.

I believe that it is not only possible to view simulation models as instruments in this way, but even advantageous. First, if simulation models are instruments, it is perfectly understandable that each LHC-collaboration comes down with its own tunes. This just means adjusting the instrument to a range of tasks, taking track of the relation between instrument and (known) ambient conditions. A procedure like this would, in contrast, make no sense if the model was to represent the goings-on within the measured system.

Second, if simulation models are instruments, then even calibrating in situ is nothing suspicious at all: Calibrating an instrument in situ means taking track of the relation between experimental inputs and measured values in the precise context into which the instrument is embedded, and this is sometimes recognised as an advantage of in situ calibration on material instruments (e.g. Cable, 2005, p. 12). It is then also unsurprising that measurements can be associated with a smaller uncertainty, since the calibration procedure eliminates the possibility of error due to unrepresentative environmental conditions.

Third, if calibrating on the very data used for measurement means eliminating possible errors in representing the ambient environmental conditions, this also serves RA’s aim of securing the result from important sources of error. It hence becomes understandable why Corcella et al. (2018, 490; emph. added) considered their procedure to not only yield “an improvement of the accuracy” but also “the robustness of the mass measurement.”

Assuming that these models, thus, function as instruments, in what sense can we regard them as reliable? The sense of reliability here is that, when calibrated to sufficiently specific experimental conditions, they can facilitate convergent QERs in ways that do not crucially depend on either model’s properties. This was fully evidenced in Sect. 4, and may be seen as an instance fail to (accurately) answer ‘why’-questions about its purported target while being sufficiently transparent (qua instrument) to allow for the sort of calibration investigated by Tal.
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of what Parker (2020, p. 462; emph. omit.) calls “reliability in a type of use”. This reliability, generating a kind of adequacy-for-purpose, is present for tool $M$ when in instances of type $C$, a user $U$, following a methodology $W$ under circumstances $B$, is likely to achieve purpose $P$ with $M$.

As we saw, in instances of simulation-infected measurements ($C$), HEP-collaborations ($U$), following a calibration procedure ($W$) that involves relevantly similar data ($B$), can achieve measurement results ($P$) that lie in sufficient proximity to one another so as to define a(n informative) common result. Furthermore, since each measurement discriminates against different hypotheses, $H$, as to the result’s potentially artefactual nature, this usage can be seen to likely serve the intended purpose. This fully establishes the sense of reliability I have in mind.

6.3 Assumption convergence: A rejoinder?

What could be countered to rehabilitate these models’ representational status? As discussed in Sect. 6.1, a common core beyond generic QCD-features could lead to ‘richer’ robust theorems, thus giving rise to a more meaningful kind of “low-level confirmation”. Furthermore, different hadronisation models are not entirely independent, as mentioned in Sect. 3.2, and hence there is reason to believe this greater common core might exist. For instance, string and cluster models both face limitations in certain mass domains, and so lighter strings are essentially treated as clusters in string models whereas heavier clusters are essentially treated as strings in cluster models (see Dissertori et al., 2003, p. 171). More generally:

The accumulation of more precise data have led the models to converge to something more similar. The string model has had successively refined perturbative evolution and the cluster model has become successively more string-like. This leads one to wonder whether nature is pointing us towards a model in which the flavour mix is largely determined by the perturbative dynamics, as in the cluster model, and their distributions largely determined by non-perturbative string dynamics. (Seymour and Marx, 2015, 309)

A possible explanation of the successful use of such converged models could hence be that they at least partially capture the truth. I mentioned before that there are some general reasons for scepticism about this sort of confirmation, but in the present context, there are also quite specific reasons.

First, recall that parametrisation in hadronisation-modelling is applied at a level where many details remain unresolved. The success of models whose parameters reside at such a level of grain cannot be clearly attributed to their underlying assumptions:

If the model agrees with the observations against which it is tested, this could be the result of “compensating errors” (namely, the model has been tuned as a whole), and if the model does not agree with the observations, one does not know which adjustable parameters (or even complete parametrisations) are wrong. (Petersen, 2000, p. 269)

Peterson here refers to climate models, and one might argue that the situation is different in HEP; for it is not the success of current models but rather the failure of older models that leads to the possibility of semi-empirical confirmation.
Second, however, the in situ calibration for increased accuracy described above pertains to quite recent models, and each collaboration keeps producing (and using) individual tunes for specific purposes. Hence, the physical meaningfulness of converged models remains impaired by the fact that parameters will be adjusted to details that should not matter for their interpretation. I thus maintain that the actual use of HEP simulation parameters spoils the indicated possibility of semi-empirical confirmation: Being able to rule out some models across all values of parameters does not render the remaining models trustworthy beyond instrumental reliability.

7 Conclusions

I have argued that CSs in HEP can be trusted in their capacity to facilitate credible experimental results when individual results are robust against changes of simulation model and consistent results are generated using different processes to simulate, analyses making use of CSs in different ways, and even different parameter-tunings. Furthermore, by combining several results so generated, it is possible to strike a balance between security and informativeness.

However, the models involved in generating these results exhibited a curious failure of robustness regarding their parameters: Choices of tune are not necessarily consistent even across the LHC, and different tunes can in principle alter CS-based predictions non-negligibly. This delicate combination of robustness and failures thereof was used to argue that, while experimental results can be trusted in the strong sense of belief, the simulation models used to generate them can be trusted only in the weak sense of acceptance as reliable instruments. The strongest reasons given for this were that hyper-specific tunes can increase experimental accuracy and that experimental collaborations each use various tunes while the physics targeted by them should be insensitive to the detailed experimental conditions.

These reservations against the models’ faithful representational status could be answered by deeper modelling and parametrisation at a higher grain, but whether this is actually possible remains a question for working physicist to answer. It would, of course, even then be possible to remain sceptical about semi-empirical confirmation from RA, but I believe that the remaining doubts would reside at a deeper level of philosophical debate (Stanford, 2006; van Fraassen, 1989).

Finally, the conclusions reached in this paper should be of interest also for other simulation-heavy fields: Climate models, like HEP simulation models, are highly entrenched (Lenhard and Winsberg, 2010), whence independent validation is impossible; and models in astrophysics exhibit similar peculiarities regarding their free parameters (Gueguen, 2019). Furthermore, due to its overall organisation and properly experimental status, HEP is subject to favourable epistemic conditions regarding the justification and use of its CSs (see Boge and Zeitnitz, 2020). Hence, conclusions drawn for HEP likely transfer to fields where the conditions are arguably less favourable.

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