

Questionable and Unquestionable in Quantum Mechanics

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Abstract

We derive the basic postulates of quantum physics from a few very simple and easily testable operational assumptions based exclusively on the relative frequencies of observable events (measurement operations and measurement outcomes). We isolate a notion which can be identified with the system's own state, in the sense that it characterizes the system's probabilistic behavior against all possible measurement operations. We investigate some important features of the possible states of the system. All those investigations remain within the framework of classical Kolmogorovian probability theory, meaning that any physical system (traditionally categorized as classical or quantum) that can be described in operational terms can be described within classical Kolmogorovian probability theory.

In the second part of the paper we show that anything that can be described in operational terms can, if we wish, be represented in the Hilbert space quantum mechanical formalism. The outcomes of each measurement can be represented by a system of pairwise orthogonal closed subspaces spanning the entire Hilbert space; the states of the system can be represented by pure state operators, and the probabilities of the outcomes can be reproduced by the usual trace formula. Each real valued quantity can be associated with a suitable self-adjoint operator, such that the possible measurement results are the eigenvalues and the outcome events are represented by the eigenspaces, according to the spectral decomposition of the operator in question.

This suggests that the basic postulates of quantum theory are in fact analytic statements: they do not tell us anything about a physical system beyond the fact that the system can be described in operational terms. This is almost true. At the end of the paper we discuss a few subtle points where the representation we obtained is not completely identical with standard quantum mechanics.

1 Introduction

The main result of this paper is an entirely operational foundation of quantum theory. Operational approach to quantum mechanics is of course not a novel idea. In the past decades, a number of great works have appeared with similar aims (e.g. Ludwig 1970; Foulis and Randall 1974; Davies 1976; Busch, Grabowski, and Lahti 1995; Spekkens 2005; Barum *et al.* 2007; 2008; Aerts 2009; Abramsky and Heunen 2016; Schmid, Spekkens, and Wolfe 2018). The novelty of our approach lies in the fact that our goal is not to translate the known theory of quantum mechanics into operational terms, or to reconstruct the theory in terms of operationally interpretable postulates. Such a “reconstruction”, as we shall see, will be only a by-product—though not a mathematically trivial one—of a general operational description. While the operational scheme we are considering does not itself refer in any way to quantum theory. It is based exclusively on the notion of observable events (measurement operations and measurement outcomes) and on general, empirically established simple laws concerning their relative frequencies. These regularities are so simple and fundamental that they are equally valid whether the physical system under study is traditionally considered to be a classical or a quantum physical phenomenon.

We describe a typical empirical scenario in the following way: One can perform different measurement operations on a physical system, each of which may have different possible outcomes. The performance of a measuring operation is regarded as a physical event on par with the measurement outcomes. Empirical data are, exclusively, the observed relative frequencies of how many times different measurement operations are performed and how many times different outcome events occur, including the joint performances of two or more measurements and the conjunctions of their outcomes. In terms of the observed relative frequencies we stipulate two empirical conditions, **(E1)** and **(E2)**, which are simple, plausible, and empirically testable.

Of course, the observed relative frequencies essentially depend on the frequencies with which the measurement operations are performed; that is, on circumstances external to the physical system under consideration; for example, on the free choice of a human. Under a further empirically testable assumption about the observed frequencies, **(E3)**, we can isolate a notion which is independent of the relative frequencies of the measurement operations and can be identified with the system’s own state; in the sense that it characterizes the system’s probabilistic behavior against all possible measurement operations. The largest part of our further investigation is at the level of generality defined by assumptions **(E1)**–**(E3)**.

In Section 3, we derive important theorems, solely from conditions **(E1)**–**(E3)**, concerning the possible states of the system. In Section 4, we characterize the time evolution of these states on the basis of a further, empirically testable assumption **(E4)**. Section 5 considers various possible ontological pictures consistent with our probabilistic notion of state.

All these investigations are expressed in terms of relative frequencies, which by definition satisfy the Kolmogorovian axioms of classical probability theory.

This means that any physical system—traditionally categorized as classical or quantum—that can be described in operational terms can be described within classical Kolmogorovian probability theory—whether we talk about the system’s probabilistic state, time evolution or ontology. In the second part of the paper, at the same time, we will show that anything that can be described in these operational terms can, if we wish, be represented in the Hilbert space quantum mechanical formalism. It will be proved that there always exists:

- a suitable Hilbert space, such that
- the outcomes of each measurement can be represented by a system of pairwise orthogonal closed subspaces, spanning the whole Hilbert space,
- the states of the system can be represented by pure state operators with suitable state vectors, and
- the probabilities of the measurement outcomes can be reproduced by the usual trace formula of quantum mechanics.

Moreover, if appropriate, one can label the possible outcomes of a measurement with numbers, and talk about them as the measured values of a physical quantity. Each such quantity

- can be associated with a suitable self-adjoint operator, such that
- the expectation value of the quantity, in all states of the system, can be reproduced by the usual trace formula applied to the associated self-adjoint operator,
- the possible measurement results are exactly the eigenvalues of the operator, and
- the corresponding outcome events are represented by the eigenspaces pertaining to the eigenvalues respectively, according to the spectral decomposition of the operator in question.

This suggests that the basic postulates of quantum theory are in fact analytic statements: they do not tell us anything about a physical system beyond the fact that the system can be described in operational terms. This is almost true. Nevertheless, it must be mentioned that the quantum-mechanics-like representation we will obtain is not completely identical with standard quantum mechanics. The interesting fact is that most of the deviations from the quantum mechanical folklore, discussed in Section 8, are related with exactly those issues in the foundations of quantum mechanics that have been hotly debated for long decades.

2 The General Operational Schema

Consider a general experimental scenario: we can perform different measurement operations denoted by $a_1, a_2, \dots, a_r, \dots, a_m$ on a physical system. We shall use the same notation a_r for the physical event that the measurement operation a_r happened. Each measurement a_r may have different outcomes denoted by $X_1^r, X_2^r, \dots, X_{n_r}^r$. Let $M = \sum_{r=1}^m n_r$, and let I^M denote the following set of indices:

$$I^M = \{i^r \mid 1 \leq r \leq m, 1 \leq i \leq n_r\} \quad (1)$$

Sometimes we perform two or more measurement operations simultaneously—that is, in the same run of the experiment. So we also consider the double, triple, and higher conjunctions of measurement operations and the possible outcome events. In general, we consider the free Boolean algebra \mathcal{A} generated by the set of all measurement operation and measurement outcome events

$$G = \{a_r\}_{r=1,2,\dots,m} \cup \{X_i^r\}_{i^r \in I^M} \quad (2)$$

with the usual Boolean operations, denoted by \wedge , \vee and \neg . Introduce the following concise notation: let S_{max}^M denote the set of the indices of all double, triple, and higher conjunctions of the outcome events in G . That is, for example, ${}_{i_1 i_2 \dots i_L}^{r_1 r_2 \dots r_L} \in S_{max}^M$ will stand for the conjunction $X_{i_1}^{r_1} \wedge X_{i_2}^{r_2} \dots \wedge X_{i_L}^{r_L}$, etc.

The event algebra \mathcal{A} has 2^{M+m} atoms, each having the form of

$$\Delta_{\vec{\varepsilon}, \vec{\eta}} = \left(\bigwedge_{i^r \in I^M} [X_i^r]^{\varepsilon_i^r} \right) \wedge \left(\bigwedge_{s=1}^m [a_s]^{\eta_s} \right) \quad (3)$$

where $\vec{\varepsilon} = (\varepsilon_i^r) \in \{0, 1\}^M$, $\vec{\eta} = (\eta_s) \in \{0, 1\}^m$, and

$$[X_i^r]^{\varepsilon_i^r} = \begin{cases} X_i^r & \text{if } \varepsilon_i^r = 1 \\ \neg X_i^r & \text{if } \varepsilon_i^r = 0 \end{cases}$$

$$[a_s]^{\eta_s} = \begin{cases} a_s & \text{if } \eta_s = 1 \\ \neg a_s & \text{if } \eta_s = 0 \end{cases}$$

And, of course, all events in algebra \mathcal{A} can be uniquely expressed as a disjunction of atoms.

Assume that we can repeat the same experimental situation as many times as needed; that is, we can prepare the same (or identical) physical system in the same way and we can repeat the same measuring operations with the same (or identical) measuring devices, etc. In every run of the experiment we observe which measurement operations are performed and which outcome events occur, including the joint performances of two or more measurements and the conjunctions of their outcomes. In this way, we observe the *relative frequencies* of all elements of the event algebra \mathcal{A} . Let π denote this relative frequency function on \mathcal{A} . Obviously, (\mathcal{A}, π) constitutes a classical probability model satisfying the

Kolmogorovian axioms. Since the relative frequencies on the whole event algebra are uniquely determined by the relative frequencies of the atoms, π can be uniquely given by

$$\pi(\Delta_{\vec{\varepsilon}, \vec{\eta}}) \quad \vec{\varepsilon} \in \{0, 1\}^M ; \vec{\eta} \in \{0, 1\}^m \quad (4)$$

The observed relative frequencies on \mathcal{A} are considered *the* empirical data, exclusively.

We do not make *a priori* assumptions about these relative frequencies. Any truth about them will be regarded as empirical fact observed in the experiment. Including for example the fact that two or more measurements $a_{r_1}, a_{r_2}, \dots, a_{r_L}$ cannot be performed simultaneously; which reveals in the observed fact that $\pi(a_{r_1} \wedge a_{r_2} \dots \wedge a_{r_L})$ *always* equals 0. Though, this “always” needs some further explanation. For, it is obviously true that the frequencies $\pi(a_r)$ sensitively depend on the will of the experimenter. Therefore, it can be the case that $\pi(a_{r_1} \wedge a_{r_2} \dots \wedge a_{r_L}) = 0$ simply because the experimenter never chooses to perform the measurements $a_{r_1}, a_{r_2}, \dots, a_{r_L}$ simultaneously. At least at first sight this seems to significantly differ from the situation when a certain combination of experiments are never performed due to objective reasons; because the simultaneous performance of the measurement operations is—as we usually express—impossible. Without entering into the metaphysical disputes about possibility–impossibility, we only say that the impossibility of a combination of measurements is a contingent fact of the world; the measuring devices and the measuring operations are such that the joint measurement $a_{r_1} \wedge a_{r_2} \dots \wedge a_{r_L}$ never occurs. Let us denote by $\mathfrak{I} \subset \mathcal{P}(\{1, 2, \dots, m\})$ (where $\mathcal{P}(A)$ is the power set of set A) the set of indices of such “impossible” conjunctions. That is, for all $2 \leq L \leq m$,

$$\pi(a_{r_1} \wedge a_{r_2} \dots \wedge a_{r_L}) = 0 \quad \text{if } \{r_1, r_2, \dots, r_L\} \in \mathfrak{I} \quad (5)$$

In contrast, let $\mathfrak{P} \subset \mathcal{P}(\{1, 2, \dots, m\})$ denote the set of indices of the “possible” conjunctions:

$$\mathfrak{P} = \left\{ \{r_1, r_2, \dots, r_L\} \in \mathcal{P}(\{1, 2, \dots, m\}) \mid 2 \leq L \leq m; \{r_1, r_2, \dots, r_L\} \notin \mathfrak{I} \right\}$$

(E1) We assume, as empirically observed fact, that every conjunction of measurements that is possible does occur with some non-zero frequency:

$$\pi(a_{r_1} \wedge a_{r_2} \dots \wedge a_{r_L}) > 0 \quad \text{if } \{r_1, r_2, \dots, r_L\} \in \mathfrak{P} \quad (6)$$

We also assume that for all $1 \leq r \leq m$,

$$\pi(a_r) > 0 \quad (7)$$

Similarly to (1), we introduce the following sets of indices:

$$\begin{aligned} S &= \{ \{i_1^{r_1} i_2^{r_2} \dots i_L^{r_L}\} \in S_{max}^M \mid \{r_1, r_2, \dots, r_L\} \in \mathfrak{P} \} \\ S_{\mathfrak{I}} &= \{ \{i_1^{r_1} i_2^{r_2} \dots i_L^{r_L}\} \in S_{max}^M \mid \{r_1, r_2, \dots, r_L\} \in \mathfrak{I} \} \end{aligned}$$

(E2) The following assumptions are also regarded as empirically observed regularities: for all $r, r' \in I^M$ and $\{r_1, r_2, \dots, r_L\} \in \mathfrak{P}$,

$$\pi(a_r \wedge X_i^r) = \pi(X_i^r) \quad (8)$$

$$\text{if } r = r' \text{ and } i \neq i' \text{ then } \pi(X_i^r \wedge X_{i'}^{r'}) = 0 \quad (9)$$

$$\sum_{\substack{k \\ (r_k \in I^M)}} \pi(X_k^r | a_r) = 1 \quad (10)$$

$$\sum_{\substack{k_1 \dots k_L \\ (r_{k_1} \dots r_{k_L} \in \mathcal{S})}} \pi(X_{k_1}^{r_{k_1}} \wedge \dots \wedge X_{k_L}^{r_{k_L}} | a_{r_1} \wedge \dots \wedge a_{r_L}) = 1 \quad (11)$$

where $\pi(\cdot | \cdot)$ denotes the usual conditional relative frequency defined by the Bayes rule— $\pi(a_r) \neq 0$ and $\pi(a_{r_1} \wedge a_{r_2} \dots \wedge a_{r_L}) \neq 0$, due to (6)–(7). That is to say, an outcome event does not occur without the performance of the corresponding measurement operation; it is never the case that two different outcomes of the same measurement occur simultaneously; whenever a measurement operation is performed, one of the possible outcomes occurs; whenever a conjunction of measurement operations is performed, one of the possible outcome combinations occurs.

In the picture we suggest, an outcome of a measurement is, primarily, a physical event, an occurrence of a certain state of affairs at the end of the measuring process; rather than obtaining a numeric value of a quantity. To give an example, the state of affairs when the rotated coil of a voltmeter takes a new position of equilibrium with the distorted spring is ontologically prior to the number on the scale to which its pointer points at that moment. Nevertheless, in some cases the measurement outcomes are labeled by real numbers that are interpreted as the “measured value” of a real-valued physical quantity:

$$\alpha_r : X_i^r \mapsto \alpha_i^r \in \mathbb{R} \quad (12)$$

In this case, at least formally, it may make sense to talk about conditional expectation value, that is the average of the measured values, given that the measurement is performed:

$$\langle \alpha_r \rangle = \sum_{i=1}^{n_r} \alpha_i^r \pi(X_i^r | a_r)$$

About all labelings α_r we will assume that $\alpha_i^r \neq \alpha_j^r$ for $i \neq j$.

3 The State of the System

Of course, the relative frequency π in (\mathcal{A}, π) depends not only on the behavior of the physical system after a certain physical preparation but also on the au-

tonomous decisions of the experimenter to perform this or that measurement operation. One can hope a scientific description of the system only if the two things can be separated. Whether this is possible is a contingent fact of the empirically observed reality, reflected in the observed relative frequencies.

Let $|S|$ denote the number of elements of S . Consider the following vector:

$$\vec{Z} = (Z_i^r, Z_{i_1 \dots i_L}^{r_1 \dots r_L}) \in \mathbb{R}^{M+|S|} \quad (13)$$

where

$$Z_i^r = \pi(X_i^r | a_r) \quad r \in I^M \quad (14)$$

and

$$Z_{i_1 \dots i_L}^{r_1 \dots r_L} = \pi(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L}) \quad \begin{matrix} r_1 \dots r_L \in S \\ i_1 \dots i_L \in S \end{matrix} \quad (15)$$

In general, even if the physical preparation of the system is identical in every run of the experiment, the conditional relative frequencies on the right hand sides of (14)–(15), hence the values of Z_i^r and $Z_{i_1 \dots i_L}^{r_1 \dots r_L}$, may vary if the actual frequencies $\{\pi(a_r)\}_{1 \leq r \leq m}$ and $\{\pi(a_{r_1} \wedge \dots \wedge a_{r_L})\}_{\{r_1, \dots, r_L\} \in \mathfrak{P}}$ vary, for example, upon the experimenter's decisions.

However, we make the following stipulation as observed empirical fact:

(E3) For all physical preparations, keeping the preparation fixed, \vec{Z} is independent of the actual nonzero values of $\{\pi(a_r)\}_{1 \leq r \leq m}$ and $\{\pi(a_{r_1} \wedge \dots \wedge a_{r_L})\}_{\{r_1, \dots, r_L\} \in \mathfrak{P}}$.

In other words, what **(E3)** says is that for all fixed physical preparations, the observed relative frequencies are such that

$$\pi(X_i^r) = Z_i^r \pi(a_r) \quad r \in I^M \quad (16)$$

$$\pi(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) = \begin{cases} Z_{i_1 \dots i_L}^{r_1 \dots r_L} \pi(a_{r_1} \wedge \dots \wedge a_{r_L}) & \begin{matrix} r_1 \dots r_L \in S \\ i_1 \dots i_L \in S \end{matrix} \\ 0 & \begin{matrix} r_1 \dots r_L \in S_j \\ i_1 \dots i_L \in S_j \end{matrix} \end{cases} \quad (17)$$

with *one and the same* $\vec{Z} = (Z_i^r, Z_{i_1 \dots i_L}^{r_1 \dots r_L})$. \vec{Z} is therefore determined only by the physical preparation. Notice that **(E3)** does not exclude that different physical preparations lead to the same \vec{Z} .

\vec{Z} can be regarded as a characterization of the system's *state* after the given physical preparation, in the sense that it characterizes the system's future probabilistic behavior against all possible measurement operations. This characterization is complete in the following sense:

Theorem 1. *State \vec{Z} together with arbitrary relative frequencies of measurements, $\{\pi(a_r)\}_{1 \leq r \leq m}$ and $\{\pi(a_{r_1} \wedge \dots \wedge a_{r_L})\}_{\{r_1, \dots, r_L\} \in \mathfrak{P}}$, uniquely determine the relative frequency function π on the whole event algebra \mathcal{A} .*

Proof. Using the same notations we introduced in (3), each atom has the form of

$$\Delta_{\vec{\varepsilon}, \vec{\eta}} = \underbrace{\left(\bigwedge_{r \in I^M} [X_i^r]^{\varepsilon_r} \right)}_{\Gamma_{\vec{\varepsilon}}} \wedge \left(\bigwedge_{s=1}^m [a_s]^{\eta_s} \right) \quad (18)$$

Notice that the part $\Gamma_{\vec{\varepsilon}} = \bigwedge_{i \in I^M} [X_i^r]^{\varepsilon_i^r}$ in (18) uniquely determines the whole $\Delta_{\vec{\varepsilon}, \vec{\eta}}$, whenever $\pi(\Delta_{\vec{\varepsilon}, \vec{\eta}}) \neq 0$. Namely, due to (8) and (10),

$$\pi(\Delta_{\vec{\varepsilon}, \vec{\eta}}) \neq 0 \text{ implies that for all } 1 \leq r \leq m, \sum_{i=1}^{n_r} \varepsilon_i^r = 0 \text{ iff } \eta_r = 0 \quad (19)$$

In other words, for each $\vec{\varepsilon} \in \{0, 1\}^M$ there is exactly one $\vec{\eta} \in \{0, 1\}^m$ for which (8) and (10) do not imply that $\pi(\Delta_{\vec{\varepsilon}, \vec{\eta}}) = 0$. Let us denote it by $\vec{\eta}(\vec{\varepsilon})$; and, for the sake of brevity, introduce the following notation: $\delta_{\vec{\varepsilon}} = \pi(\Delta_{\vec{\varepsilon}, \vec{\eta}(\vec{\varepsilon})})$. (It is not necessarily the case that $\delta_{\vec{\varepsilon}} \neq 0$. For example, the empirical fact (9) will be accounted for in terms of the values on the right hand side of (23) below.)

It must be also noticed that $\{\Gamma_{\vec{\varepsilon}}\}_{\vec{\varepsilon} \in \{0, 1\}^M}$ constitute the atoms of the free Boolean algebra \mathcal{A}^M generated by the set $\{X_i^r\}_{i \in I^M}$. Events X_i^r and $X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}$ on the right hand sides of (14)–(15) are elements of \mathcal{A}^M , and have therefore a unique decomposition into disjunction of atoms of \mathcal{A}^M . Accordingly, taking into account (19), we have

$$\sum_{\vec{\varepsilon} \in \{0, 1\}^M} \delta_{\vec{\varepsilon}} = 1 \quad (20)$$

$$\sum_{\vec{\varepsilon} \in \{0, 1\}^M} {}^r R_{\vec{\varepsilon}} \delta_{\vec{\varepsilon}} = \pi(X_i^r) = Z_i^r \pi(a_r) \quad {}^r i \in I^M \quad (21)$$

$$\begin{aligned} \sum_{\vec{\varepsilon} \in \{0, 1\}^M} {}^{r_1 \dots r_L} R_{\vec{\varepsilon}} \delta_{\vec{\varepsilon}} &= \pi(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) \\ &= Z_{i_1 \dots i_L}^{r_1 \dots r_L} \pi(a_{r_1} \wedge \dots \wedge a_{r_L}) \quad {}^{r_1 \dots r_L} i_1 \dots i_L \in S \end{aligned} \quad (22)$$

$$\sum_{\vec{\varepsilon} \in \{0, 1\}^M} {}^{r_1 \dots r_L} R_{\vec{\varepsilon}} \delta_{\vec{\varepsilon}} = \pi(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) = 0 \quad {}^{r_1 \dots r_L} i_1 \dots i_L \in S_{\mathcal{J}} \quad (23)$$

with

$$\begin{aligned} {}^r R_{\vec{\varepsilon}} &= \begin{cases} 1 & \text{if } \Gamma_{\vec{\varepsilon}} \subseteq X_i^r \\ 0 & \text{if } \Gamma_{\vec{\varepsilon}} \not\subseteq X_i^r \end{cases} \\ {}^{r_1 \dots r_L} R_{\vec{\varepsilon}} &= \begin{cases} 1 & \text{if } \Gamma_{\vec{\varepsilon}} \subseteq X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} \\ 0 & \text{if } \Gamma_{\vec{\varepsilon}} \not\subseteq X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} \end{cases} \end{aligned}$$

where \subseteq is meant in the sense of the partial ordering in \mathcal{A}^M .

Now, (20)–(23) constitute a system of $1 + M + |S_{max}^M| = 2^M$ linear equations with 2^M unknowns $\delta_{\vec{\varepsilon}}, \vec{\varepsilon} \in \{0, 1\}^M$. The equations are linearly independent due to the uniqueness of decomposition into disjunction of atoms of \mathcal{A}^M , and due to the fact that there are only conjunctions on the right hand side. (A similar equation for, say, $X_{i_1}^{r_1} \vee X_{i_2}^{r_2}$ could be expressed as the sum of equations for $X_{i_1}^{r_1}$ and $X_{i_2}^{r_2}$ minus the one for $X_{i_1}^{r_1} \wedge X_{i_2}^{r_2}$.) Therefore, the system has a unique solution for all $\delta_{\vec{\varepsilon}}$, that is, for the relative frequencies of $\{\Delta_{\vec{\varepsilon}, \vec{\eta}(\vec{\varepsilon})}\}_{\vec{\varepsilon} \in \{0, 1\}^M}$. The rest of the atoms of \mathcal{A} have zero relative frequency. \square

Thus, the notion of state we introduced complies with the widespread intuition about the notion of state within a probabilistic and operational context. As Lucien Hardy puts it:

The state associated with a particular preparation is defined to be (that thing represented by) any mathematical object that can be used to determine the probability associated with the outcomes of any measurement that may be performed on a system prepared by the given preparation. (2008, p. 2)

Such a typical formulation of the notion of state, however, results in the possibility of misunderstanding. It must be clear that the state, in itself, does not determine the probabilities of the measurement outcome events; only the state of the system \vec{Z} and the relative frequencies of the measurements $\{\pi(a_r)\}_{1 \leq r \leq m}$ and $\{\pi(a_{r_1} \wedge \dots \wedge a_{r_L})\}_{\{r_1, \dots, r_L\} \in \mathfrak{P}}$ together. And the fact that the frequencies of the measurements in (16)–(17) can be arbitrary does not imply that the components of \vec{Z}

$$\{Z_i^r, Z_{i_1 \dots i_L}^{r_1 \dots r_L}\}_{i \in I^M; r_1 \dots r_L \in S}$$

constitute relative frequencies of the corresponding outcome events

$$\{X_i^r, X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}\}_{i \in I^M; r_1 \dots r_L \in S}$$

(or events whatsoever), as will be shown in Section 5.

In contrast, it is essential in our present analysis that the measurement operations are treated on par with the outcome events; they belong to the ontology. However, as it is clearly seen from (20)–(23), the notion of \vec{Z} detaches the “system’s contribution” to the totality of statistical facts observed in the measurements from the “experimenter’s contribution”.

Still, the state of the system depends not only on the features intrinsic to the system in itself, but also on the content of \mathfrak{I} , i.e., which combinations of measuring operations cannot be performed simultaneously. This means that the measuring devices and measuring operations, by means of which we establish the empirically meaningful semantics of our physical description of the system, play a *constitutive* role in the notion of state *attributed to the system*. This kind of constitutive role of the semantic conventions is however completely natural in all empirically meaningful physical theories (Szabó 2020).

The following lemma will be important for our further investigations:

Lemma 2. *For all states,*

$$Z_{i_1 \dots i_L}^{r_1 \dots r_L} \leq \min \left\{ Z_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}} \right\}_{\{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\}} \quad (24)$$

where ${}_{i_1 \dots i_L}^{r_1 \dots r_L} \in S$.

Proof. It is known that similar inequality holds for arbitrary relative frequencies. Therefore,

$$\pi(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) \leq \min \left\{ \pi(X_{i_{\gamma_1}}^{r_{\gamma_1}} \wedge \dots \wedge X_{i_{\gamma_{L-1}}}^{r_{\gamma_{L-1}}}) \right\}_{\{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\}} \quad (25)$$

for all $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix} \in S_{max}^M$, and

$$\pi(a_{r_1} \wedge \dots \wedge a_{r_L}) \leq \min \left\{ \pi \left(a_{r_{\gamma_1}} \wedge \dots \wedge a_{r_{\gamma_{L-1}}} \right) \right\}_{\{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\}} \quad (26)$$

for all $2 \leq L \leq m$, $1 \leq r_1, \dots, r_L \leq m$. It follows from the definition of state that

$$\pi \left(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} \right) = Z_{i_1 \dots i_L}^{r_1 \dots r_L} \pi(a_{r_1} \wedge \dots \wedge a_{r_L}) \quad (27)$$

$$\pi \left(X_{i_{\gamma_1}}^{r_{\gamma_1}} \wedge \dots \wedge X_{i_{\gamma_{L-1}}}^{r_{\gamma_{L-1}}} \right) = Z_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}} \pi \left(a_{r_{\gamma_1}} \wedge \dots \wedge a_{r_{\gamma_{L-1}}} \right) \quad (28)$$

for all $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix} \in S$ and $\{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\}$. Consequently, from (25) we have

$$\frac{Z_{i_1 \dots i_L}^{r_1 \dots r_L}}{Z_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}}} \leq \frac{\pi \left(a_{r_{\gamma_1}} \wedge \dots \wedge a_{r_{\gamma_{L-1}}} \right)}{\pi \left(a_{r_1} \wedge \dots \wedge a_{r_L} \right)} \quad (29)$$

Since, according to the definition of state, (27)–(28) hold for all possible relative frequencies $\{\pi(a_r)\}_{1 \leq r \leq m}$ and $\{\pi(a_{r_1} \wedge \dots \wedge a_{r_L})\}_{\{r_1, \dots, r_L\} \in \mathfrak{P}}$, inequality (29) must hold for the minimum value of the right hand side, which is equal to 1, due to (26). And this is the case for all $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix} \in S$ and $\{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\}$. \square

It is of course an empirical question what states a system has after different physical preparations. In what follows, we will answer the question: what can we say about the “space” of theoretically possible states of a system? Where by “theoretically possible states” we mean all vectors constructed by means of definition (13)–(15) from arbitrary relative frequencies satisfying (6)–(11) and (16)–(17). Here we should note that the general probabilistic description includes the possibility—again, as an eventual empirical fact observed from the frequencies (4)—that the system is deterministic, meaning that $\vec{Z} \in \{0, 1\}^{M+|S|}$, or at least it behaves deterministically in some states.

We will show that the possible state vectors constitute a closed convex polytope in $\mathbb{R}^{M+|S|}$, which we will denote by $\varphi(M, S)$. First we will prove an important lemma.

Lemma 3. *If \vec{Z}_1 and \vec{Z}_2 are possible states then their convex linear combination $\vec{Z}_3 = \lambda_1 \vec{Z}_1 + \lambda_2 \vec{Z}_2$ ($\lambda_1, \lambda_2 \geq 0$, $\lambda_1 + \lambda_2 = 1$) also constitutes a possible state.*

Proof. According to the definition of state, the observed relative frequencies of the measurement outcomes in the two states are

$$\pi_1(X_i^r) = Z_{i_1}^r \pi_1(a_r) \quad (30)$$

$$\pi_1 \left(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} \right) = Z_{i_1 \dots i_L}^{r_1 \dots r_L} \pi_1 \left(a_{r_1} \wedge \dots \wedge a_{r_L} \right) \quad (31)$$

and

$$\pi_2(X_i^r) = Z_{i_1}^r \pi_2(a_r) \quad (32)$$

$$\pi_2 (X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) = Z_{2_{i_1 \dots i_L}^{r_1 \dots r_L}} \pi_2 (a_{r_1} \wedge \dots \wedge a_{r_L}) \quad (33)$$

for all $r_i \in I^M$ and $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix} \in S$. Due to **(E3)**, $\pi_1(a_r)$ and $\pi_1(a_{r_1} \wedge \dots \wedge a_{r_L})$ as well as $\pi_2(a_r)$ and $\pi_2(a_{r_1} \wedge \dots \wedge a_{r_L})$ can be arbitrary relative frequencies satisfying (5)–(7). Therefore, without loss of generality, we can take the case of

$$\begin{aligned} \pi_1(a_r) &= \pi_2(a_r) = \pi_0(a_r) \\ \pi_1(a_{r_1} \wedge \dots \wedge a_{r_L}) &= \pi_2(a_{r_1} \wedge \dots \wedge a_{r_L}) = \pi_0(a_{r_1} \wedge \dots \wedge a_{r_L}) \end{aligned}$$

Now, consider the convex linear combination $\pi_3 = \lambda_1 \pi_1 + \lambda_2 \pi_2$. Obviously, π_3 satisfies (6)–(10), and

$$\begin{aligned} \pi_3(a_r) &= \pi_0(a_r) \\ \pi_3(a_{r_1} \wedge \dots \wedge a_{r_L}) &= \pi_0(a_{r_1} \wedge \dots \wedge a_{r_L}) \end{aligned}$$

Accordingly, we have

$$\begin{aligned} \pi_3(X_i^r) &= \lambda_1 \pi_1(X_i^r) + \lambda_2 \pi_2(X_i^r) = (\lambda_1 Z_{1_i}^r + \lambda_2 Z_{2_i}^r) \pi_3(a_r) \\ \pi_3(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) &= \lambda_1 \pi_1(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) + \lambda_2 \pi_2(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}) \\ &= (\lambda_1 Z_{1_{i_1 \dots i_L}^{r_1 \dots r_L}} + \lambda_2 Z_{2_{i_1 \dots i_L}^{r_1 \dots r_L}}) \pi_3(a_{r_1} \wedge \dots \wedge a_{r_L}) \end{aligned}$$

This means that $\vec{Z}_3 = \lambda_1 \vec{Z}_1 + \lambda_2 \vec{Z}_2$ satisfies condition (16)–(17), as $\pi_3(a_r)$ and $\pi_3(a_{r_1} \wedge \dots \wedge a_{r_L})$ can be arbitrary frequencies satisfying (5)–(7). That is, \vec{Z}_3 complies with the definition of state, meaning that \vec{Z}_3 is a possible state of the system. \square

Now we turn to the question of the “space” of possible states. Let $\vec{e}_i^r, \vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L} \in \mathbb{R}^{M+|S|}$ denote the r_i -th and $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix}$ -th coordinate base vector of $\mathbb{R}^{M+|S|}$, where $r_i \in I^M$ and $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix} \in S$, and let $\vec{f} = (f_i^r, f_{i_1 \dots i_L}^{r_1 \dots r_L}) \in \mathbb{R}^{M+|S|}$ denote an arbitrary vector.

The empirical facts **(E1)**–**(E3)**, partly through Lemmas 2–3, imply that the possible state vectors constitute a closed convex polytope $\varphi(M, S) \subset \mathbb{R}^{M+|S|}$ defined by the following system of linear inequalities:

$$f_i^r \geq 0 \quad (34)$$

$$f_i^r \leq 1 \quad (35)$$

$$f_{i_1 \dots i_L}^{r_1 \dots r_L} \geq 0 \quad (36)$$

$$f_{i_1 \dots i_L}^{r_1 \dots r_L} - f_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}} \leq 0 \quad \{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\} \quad (37)$$

$$\sum_k f_k^r = 1 \quad (38)$$

$$\left(\begin{smallmatrix} r \\ k \end{smallmatrix} \in I^M \right)$$

$$\sum_{\substack{k_1, k_2, \dots, k_L \\ \begin{smallmatrix} r_1 \dots r_L \\ k_1 \dots k_L \end{smallmatrix} \in S}} f_{k_1 \dots k_L}^{r_1 \dots r_L} = 1 \quad (39)$$

$$f_{i'_1 \dots i'_L}^{r'_1 \dots r'_L} = 0 \quad r'_1 \dots r'_L \in S_0 \quad (40)$$

for all $r_i \in I^M$, $r_1 \dots r_L \in S$, and

$$S_0 = \left\{ r_1 \dots r_L \in S \mid r_{\gamma_1} = r_{\gamma_2}, i_{\gamma_1} \neq i_{\gamma_2}, \{\gamma_1, \gamma_2\} \subset \{1, \dots, L\} \right\}$$

Denote by $l(M, S) \subset \mathbb{R}^{M+|S|}$ the closed convex polytope defined by the first group of inequalities (34)–(37). As is well known (Pitowsky 1989, pp. 51 and 65), the vertices of $l(M, S)$ are all the vectors $\vec{v} \in \mathbb{R}^{M+|S|}$ such that

- (a) $v_i^r, v_{i_1 \dots i_L}^{r_1 \dots r_L} \in \{0, 1\}$ for all $r_i \in I^M$ and $r_1 \dots r_L \in S$.
- (b) $v_{i_1 \dots i_L}^{r_1 \dots r_L} \leq \prod_{\{\gamma_1, \gamma_2, \dots, \gamma_{L-1}\} \subset \{1, 2, \dots, L\}} v_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}}$ for all $r_1 \dots r_L \in S$.

A vertex is called classical if the equality holds everywhere in (b), and non-classical otherwise.

Obviously, $\varphi(M, S) \subseteq l(M, S)$. What can be said about the vertices of $\varphi(M, S)$?

Lemma 4. *The vertices of $\varphi(M, S)$ are all the vectors $\vec{f} \in \varphi(M, S)$ such that $f_i^r, f_{i_1 \dots i_L}^{r_1 \dots r_L} \in \{0, 1\}$ for all $r_i \in I^M$ and $r_1 \dots r_L \in S$.*

Proof. One direction is trivial: if $\vec{f} \in \varphi(M, S)$ and $f_i^r, f_{i_1 \dots i_L}^{r_1 \dots r_L} \in \{0, 1\}$ for all $r_i \in I^M$ and $r_1 \dots r_L \in S$, then \vec{f} is a vertex. For, if there exist $\vec{f}', \vec{f}'' \in \varphi(M, S)$ such that $\vec{f} = \lambda \vec{f}' + (1 - \lambda) \vec{f}''$ with some $0 < \lambda < 1$, then obviously $\vec{f}' = \vec{f}'' = \vec{f}$.

The proof of the other direction is quite involved. For a more concise notation, introduce the following sets of indices:

$$\begin{aligned} I &= \left\{ 1 \mid_i^r, 2 \mid_i^r, 3 \mid_{i_1 \dots i_L}^{r_1 \dots r_L}, 4 \mid_{i_1 \dots i_L}^{r_1 \dots r_L} \mid_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}}, 5 \mid_r, 6 \mid_{r_1 \dots r_L}, 7 \mid_{i'_1 \dots i'_L}^{r'_1 \dots r'_L} \mid \text{for all} \right. \\ &\quad \left. r_i \in I^M, r_1 \dots r_L \in S, r'_1 \dots r'_L \in S_0, \text{ and } \{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\} \right\} \\ I^0 &= \left\{ 1 \mid_i^r, 2 \mid_i^r, 3 \mid_{i_1 \dots i_L}^{r_1 \dots r_L}, 4 \mid_{i_1 \dots i_L}^{r_1 \dots r_L} \mid_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}} \mid \text{for all } r_i \in I^M, r_1 \dots r_L \in S, \right. \\ &\quad \left. \text{and } \{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\} \right\} \\ I^+ &= \left\{ 5 \mid_r, 6 \mid_{r_1 \dots r_L}, 7 \mid_{i'_1 \dots i'_L}^{r'_1 \dots r'_L} \mid \text{for all } 1 \leq r \leq m, \{r_1 \dots r_L\} \in \mathfrak{P}, \right. \\ &\quad \left. \text{and } r'_1 \dots r'_L \in S_0 \right\} \end{aligned}$$

Obviously, $I = I^0 \cup I^+$ and $I^0 \cap I^+ = \emptyset$. Rewrite (34)–(40) in the following standard form:

$$\langle \vec{\omega}_\mu, \vec{f} \rangle - b_\mu \leq 0 \quad \text{for all } \mu \in I^0 \quad (41)$$

$$\langle \vec{\omega}_\mu, \vec{f} \rangle - b_\mu = 0 \quad \text{for all } \mu \in I^+ \quad (42)$$

with the following $\vec{\omega}_\mu \in \mathbb{R}^{M+|S|}$ and $b_\mu \in \mathbb{R}$:

$$\vec{\omega}_{1|i}^r = (0 \dots 0 \underbrace{-1}_{i} 0 \dots 0) \quad (43)$$

$$b_{1|i}^r = 0 \quad (44)$$

$$\vec{\omega}_{2|i}^r = (0 \dots 0 \underbrace{1}_{i} 0 \dots 0) \quad (45)$$

$$b_{2|i}^r = 1 \quad (46)$$

$$\vec{\omega}_{3|i_1 \dots i_L}^{r_1 \dots r_L} = (0 \dots 0 \underbrace{-1}_{i_1 \dots i_L} 0 \dots 0) \quad (47)$$

$$b_{3|i_1 \dots i_L}^{r_1 \dots r_L} = 0 \quad (48)$$

$$\vec{\omega}_{4|i_1 \dots i_L}^{r_1 \dots r_L} = (0 \dots 0 \underbrace{-1}_{i_{\gamma_1} \dots i_{\gamma_{L-1}}} 0 \dots 0 \underbrace{1}_{i_1 \dots i_L} 0 \dots 0) \quad (49)$$

$$b_{4|i_1 \dots i_L}^{r_1 \dots r_L} = 0 \quad (50)$$

$$\vec{\omega}_{5|r} = (0 \dots 0 \underbrace{1}_{1} \underbrace{1}_{2} \underbrace{1}_{3} \dots \underbrace{1}_{n_r} 0 \dots 0) \quad (51)$$

$$b_{5|r} = 1 \quad (52)$$

$$\vec{\omega}_{6|r_1 \dots r_L} = (0 \dots 0 \underbrace{1}_{1 \dots 1} \underbrace{1}_{2 \dots 1} \dots \underbrace{1}_{n_{r_1} n_{r_2} \dots n_{r_L}} 0 \dots 0) \quad (53)$$

$$b_{6|r_1 \dots r_L} = 1 \quad (54)$$

$$\vec{\omega}_{7|i'_1 \dots i'_L}^{r'_1 \dots r'_L} = (0 \dots 0 \underbrace{1}_{i'_1 \dots i'_L} 0 \dots 0) \quad (55)$$

$$b_{7|i'_1 \dots i'_L}^{r'_1 \dots r'_L} = 0 \quad (56)$$

where $i \in I^M$, $i_1 \dots i_L \in S$, $\{\gamma_1, \dots, \gamma_{L-1}\} \subset \{1, \dots, L\}$, and $i'_1 \dots i'_L \in S_0$. Notice that $l(M, S)$ is defined by (41).

For an arbitrary $\vec{f} \in l(M, S)$ we define the following sets:

$$I_{\vec{f}} = \left\{ \mu \in I \mid \langle \vec{\omega}_\mu, \vec{f} \rangle - b_\mu = 0 \right\}$$

$$I_{\vec{f}}^0 = \left\{ \mu \in I^0 \mid \langle \vec{\omega}_\mu, \vec{f} \rangle - b_\mu = 0 \right\}$$

Notice that if $\vec{f} \in \varphi(M, S)$, then $I_{\vec{f}} = I_{\vec{f}}^0 \cup I^+$, due to the fact that (38)–(40) can be satisfied only with equality.

$I_{\vec{f}}$ constitutes the so called ‘active index set’ for $\vec{f} \in \varphi(M, S)$; and according to a known theorem (see Theorem 12 in Appendix), \vec{f} is a vertex of $\varphi(M, S)$ if and only if

$$\text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}} = \mathbb{R}^{M+|S|} \quad (57)$$

Similarly, a vector $\vec{f} \in l(M, S)$ is a vertex of $l(M, S)$ if and only if

$$\text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}^0} = \mathbb{R}^{M+|S|} \quad (58)$$

For all $\vec{f} \in l(M, S)$ define

$$\begin{aligned} J_{\vec{f}} &= \{i \mid i^r \in I^M \text{ and } 0 < f_i^r < 1\} \\ J'_{\vec{f}} &= \{i_1 \dots i_L \mid i_1^{r_1} \dots i_L^{r_L} \in S \text{ and } 0 < f_{i_1 \dots i_L}^{r_1 \dots r_L} < 1\} \end{aligned}$$

Notice that for all $i^r \in I^M$ and $i_1^{r_1} \dots i_L^{r_L} \in S$,

$$\vec{e}_i^r \in \text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}^0} \quad \text{if } f_i^r \in \{0, 1\} \quad (59)$$

$$\vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L} \in \text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}^0} \quad \text{if } f_{i_1 \dots i_L}^{r_1 \dots r_L} \in \{0, 1\} \quad (60)$$

since the corresponding inequalities (34)–(37) must hold with equality. The only case that requires a bit of reflection is when $f_{i_1 \dots i_L}^{r_1 \dots r_L} = 1$. For example, if $f_{i_1 i_2}^{r_1 r_2} = 1$ then (37) is satisfied with equality, so that $f_{i_1}^{r_1} = 1$, therefore (35) is also satisfied with equality. Consequently,

$$\begin{aligned} \vec{\omega}_2 |_{i_1}^{r_1} &\in \text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}^0} \\ \vec{\omega}_4 |_{i_1 i_2}^{r_1 r_2} |_{i_1}^{r_1} &\in \text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}^0} \end{aligned}$$

At the same time, as it can be seen from (45) and (49),

$$\vec{e}_{i_1 i_2}^{r_1 r_2} = \vec{\omega}_2 |_{i_1}^{r_1} + \vec{\omega}_4 |_{i_1 i_2}^{r_1 r_2} |_{i_1}^{r_1} \in \text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}^0}$$

This can be recursively continued for the triple and higher conjunction indices.

Assume now that $\vec{f} \in \varphi(M, S)$ is such that $J_{\vec{f}} \cup J'_{\vec{f}} \neq \emptyset$, and at the same time it is a vertex of $\varphi(M, S)$, that is, (57) is satisfied. We are going to show that this leads to contradiction.

Due to (59)–(60), the assumption that \vec{f} is a vertex implies that all base vectors of $\mathbb{R}^{M+|S|}$ must belong to $\text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}^0}$ save for some \vec{e}_i^r 's with $i^r \in J_{\vec{f}}$ and/or some $\vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L}$'s with $i_1^{r_1} \dots i_L^{r_L} \in J'_{\vec{f}}$. On the other hand, \vec{f} being a vertex implies that (57) holds, therefore

$$\begin{aligned} \vec{e}_i^r &\in \text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}} \quad \text{for all } i^r \in J_{\vec{f}} \\ \vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L} &\in \text{span} \{\vec{\omega}_\mu\}_{\mu \in I_{\vec{f}}} \quad \text{for all } i_1^{r_1} \dots i_L^{r_L} \in J'_{\vec{f}} \end{aligned}$$

Taking into account that $I_{\bar{f}} = I_{\bar{f}}^0 \cup I^+$, it means that for all ${}^r_i \in J_{\bar{f}}$ and arbitrary $\tau_i^r \neq 0$ there exist vectors

$${}^r_i \vec{v} \in \text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\bar{f}}^0} \quad (61)$$

such that,

$$\begin{aligned} \tau_i^r \vec{e}_i^r &= {}^r_i \vec{v} + \sum_{s=1}^m {}^r_i \kappa_s \vec{\omega}_{5|s} + \sum_{\{r_1, \dots, r_{L'}\} \in \mathfrak{P}} {}^r_i \kappa'_{r_1 \dots r_{L'}} \vec{\omega}_{6|r_1 \dots r_{L'}} \\ &+ \sum_{\substack{r'_1 \dots r'_{L'} \in S_0 \\ i'_1 \dots i'_L \in S_0}} {}^r_i \lambda_{r'_1 \dots r'_{L'}} \vec{\omega}_{7|i'_1 \dots i'_L} \end{aligned} \quad (62)$$

with some real numbers ${}^r_i \kappa_s$, ${}^r_i \kappa'_{r_1 \dots r_{L'}}$, and ${}^r_i \lambda_{r'_1 \dots r'_{L'}}$. From the definitions of $\vec{\omega}_{5|r}$, $\vec{\omega}_{6|r_1 \dots r_{L'}}$, and $\vec{\omega}_{7|i'_1 \dots i'_L}$ in (43)–(56) we can write:

$$\begin{aligned} \tau_i^r \vec{e}_i^r &= {}^r_i \vec{v} + \sum_{j \in I^M} {}^r_i \kappa_s \vec{e}_j^s + \sum_{\substack{s_1 \dots s_{L'} \in S \\ j_1 \dots j_{L'} \in S}} {}^r_i \kappa'_{s_1 \dots s_{L'}} \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \\ &+ \sum_{\substack{r'_1 \dots r'_{L'} \in S_0 \\ i'_1 \dots i'_L \in S_0}} {}^r_i \lambda_{r'_1 \dots r'_{L'}} \vec{e}_{i'_1 \dots i'_L}^{r'_1 \dots r'_{L'}} \end{aligned} \quad (63)$$

Mutatis mutandis, we have the same equation for $\vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L}$ for all ${}^{r_1 \dots r_L}_{i_1 \dots i_L} \in J'_{\bar{f}}$ with arbitrary $\tau_{i_1 \dots i_L}^{r_1 \dots r_L} \neq 0$ and with some numbers ${}^{r_1 \dots r_L}_{i_1 \dots i_L} \kappa_s$, ${}^{r_1 \dots r_L}_{i_1 \dots i_L} \kappa'_{r_1 \dots r_{L'}}$, and ${}^{r_1 \dots r_L}_{i_1 \dots i_L} \lambda_{r'_1 \dots r'_{L'}}$:

$$\begin{aligned} \tau_{i_1 \dots i_L}^{r_1 \dots r_L} \vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L} &= {}^{r_1 \dots r_L}_{i_1 \dots i_L} \vec{v} + \sum_{j \in I^M} {}^{r_1 \dots r_L}_{i_1 \dots i_L} \kappa_s \vec{e}_j^s + \sum_{\substack{s_1 \dots s_{L'} \in S \\ j_1 \dots j_{L'} \in S}} {}^{r_1 \dots r_L}_{i_1 \dots i_L} \kappa'_{s_1 \dots s_{L'}} \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \\ &+ \sum_{\substack{r'_1 \dots r'_{L'} \in S_0 \\ i'_1 \dots i'_L \in S_0}} {}^{r_1 \dots r_L}_{i_1 \dots i_L} \lambda_{r'_1 \dots r'_{L'}} \vec{e}_{i'_1 \dots i'_L}^{r'_1 \dots r'_{L'}} \end{aligned} \quad (64)$$

With some rearrangement, from (63) we have

$$\begin{aligned} &\sum_{\substack{s \in J_{\bar{f}} \\ j \neq i}} {}^r_i \kappa_s \vec{e}_j^s + ({}^r_i \kappa_r - \tau_i^r) \vec{e}_i^r + \sum_{\substack{s_1 \dots s_{L'} \in J'_{\bar{f}} \\ j_1 \dots j_{L'} \in J'_{\bar{f}}}} {}^r_i \kappa'_{s_1 \dots s_{L'}} \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \\ &= - \sum_{\substack{r'_1 \dots r'_{L'} \in S_0 \\ i'_1 \dots i'_L \in S_0}} {}^r_i \lambda_{r'_1 \dots r'_{L'}} \vec{e}_{i'_1 \dots i'_L}^{r'_1 \dots r'_{L'}} - \sum_{\substack{s_1 \dots s_{L'} \in S \\ j_1 \dots j_{L'} \in S \\ \substack{s_1 \dots s_{L'} \\ j_1 \dots j_{L'}} \notin J'_{\bar{f}}}} {}^r_i \kappa'_{s_1 \dots s_{L'}} \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \end{aligned}$$

$$- \sum_{\substack{s \\ j \in I^M \\ j \notin J_{\bar{f}}}} \kappa_s \vec{e}_j^s - \tau_i \vec{v} \quad (65)$$

for all $r_i \in J_{\bar{f}}$.

Similarly, from (64) we have

$$\begin{aligned} & \sum_{j \in J_{\bar{f}}} \kappa_s \vec{e}_j^s + \sum_{\substack{s_1 \dots s_{L'} \in J'_{\bar{f}} \\ j_1 \dots j_{L'} \neq r_1 \dots r_L \\ j_1 \dots j_{L'} \neq i_1 \dots i_L}} \kappa_{s_1 \dots s_{L'}} \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \\ & + \left(\kappa_{r_1 \dots r_L} - \tau_{i_1 \dots i_L} \right) \vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L} \\ = & - \sum_{\substack{r'_1 \dots r'_{L'} \in S_0 \\ i'_1 \dots i'_{L'}}} \kappa_{r'_1 \dots r'_{L'}} \vec{e}_{i'_1 \dots i'_{L'}}^{r'_1 \dots r'_{L'}} \\ & - \sum_{\substack{s_1 \dots s_{L'} \in S \\ j_1 \dots j_{L'} \notin J'_{\bar{f}} \\ j_1 \dots j_{L'} \notin J_{\bar{f}}}} \kappa_{s_1 \dots s_{L'}} \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \\ & - \sum_{\substack{s \\ j \in I^M \\ j \notin J_{\bar{f}}}} \kappa_s \vec{e}_j^s - \tau_{i_1 \dots i_L} \vec{v} \quad (66) \end{aligned}$$

for all $r_1 \dots r_L \in J'_{\bar{f}}$.

Denote the right hand side of (65) by \vec{B}_i and the right hand side of (66) by $\vec{B}_{r_1 \dots r_L}$. Notice that the vectors \vec{B}_i and $\vec{B}_{r_1 \dots r_L}$ are contained in $\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\bar{f}}^0}$, due to (61), and (59)–(60). So, in (65)–(66), together, we have a system of linear equations with vector-variables $\{ \vec{e}_j^s \}_{s \in J_{\bar{f}}}$ and $\{ \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \}_{s_1 \dots s_{L'} \in J'_{\bar{f}}}$, which can be written in the following form:

$$\sum_{j \in J_{\bar{f}}, s_1 \dots s_{L'} \in J'_{\bar{f}}} \beta_{\substack{r \\ i, i_1 \dots i_L}} \left(\substack{r \\ i, i_1 \dots i_L} \right)_{\substack{s \\ j, j_1 \dots j_{L'}}} \left(\vec{e}_j^s, \vec{e}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \right) = \left(\vec{B}_i, \vec{B}_{r_1 \dots r_L} \right) \quad (67)$$

where $\beta_{\substack{r \\ i, i_1 \dots i_L}} \left(\substack{s \\ j, j_1 \dots j_{L'}} \right)$ is a $(|J_{\bar{f}}| + |J'_{\bar{f}}|) \times (|J_{\bar{f}}| + |J'_{\bar{f}}|)$ matrix with diagonal elements

$$\begin{aligned} \beta_{ii}^{rr} &= \kappa_r - \tau_i^r \\ \beta_{i_1 \dots i_L, i_1 \dots i_L}^{r_1 \dots r_L} &= \kappa_{r_1 \dots r_L} - \tau_{i_1 \dots i_L}^{r_1 \dots r_L} \end{aligned}$$

The off diagonal elements depend only on κ_s 's and $\kappa_{s_1 \dots s_{L'}}$'s. Since the numbers $\tau_i^r \neq 0$ and $\tau_{i_1 \dots i_L}^{r_1 \dots r_L} \neq 0$ in the diagonal can be chosen arbitrarily, we

may assume that $\det \beta \binom{r_1 \dots r_L}{i_1 \dots i_L} \binom{s_1 \dots s_{L'}}{j_1 \dots j_{L'}} \neq 0$. Therefore, the system of linear equations (67) has a unique solution for all vector-variables \vec{e}_i^r and $\vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L}$, namely,

$$(\vec{e}_i^r, \vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L}) = \sum_{\substack{s \in J_{\vec{f}}, \\ j_1 \dots j_{L'} \in J'_{\vec{f}}}} \beta^{-1} \binom{r_1 \dots r_L}{i_1 \dots i_L} \binom{s_1 \dots s_{L'}}{j_1 \dots j_{L'}} \left(\vec{B}_j^s, \vec{B}_{j_1 \dots j_{L'}}^{s_1 \dots s_{L'}} \right)$$

Taking into account that $\vec{B}_i^r, \vec{B}_{i_1 \dots i_L}^{r_1 \dots r_L} \in \text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}^0}$, this all means that for all $r \in J_{\vec{f}}$, the base vectors \vec{e}_i^r , and for all $r_1 \dots r_L \in J'_{\vec{f}}$, the base vectors $\vec{e}_{i_1 \dots i_L}^{r_1 \dots r_L}$ can be expressed as linear combinations of vectors contained in $\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}^0}$. As all the rest of base vectors belong to $\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}^0}$ (as we have already mentioned above), we have

$$\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}^0} = \mathbb{R}^{M+|S|}$$

meaning that \vec{f} must be a vertex of $l(M, S)$. Due to the fact that all components of a vertex of $l(M, S)$ are necessarily 0 or 1, there cannot exist a vertex $\vec{f} \in \varphi(M, S)$ with $0 < f_i^r < 1$ and/or $0 < f_{i_1 \dots i_L}^{r_1 \dots r_L} < 1$. \square

All this means that the vertices of $\varphi(M, S)$ are those vertices of $l(M, S)$ which satisfy the further restrictions (38)–(40).

To sum up, the “space” of possible states is a closed convex polytope $\varphi(M, S) \subset \mathbb{R}^{M+|S|}$ whose vertices are the vectors $\vec{w} \in \mathbb{R}^{M+|S|}$ such that

- (a) $w_i^r, w_{i_1 \dots i_L}^{r_1 \dots r_L} \in \{0, 1\}$ for all $r \in I^M$ and $r_1 \dots r_L \in S$.
- (b) $w_{i_1 \dots i_L}^{r_1 \dots r_L} \leq \prod_{\{\gamma_1 \dots \gamma_{L-1}\} \subset \{1, \dots, L\}} w_{i_{\gamma_1} \dots i_{\gamma_{L-1}}}^{r_{\gamma_1} \dots r_{\gamma_{L-1}}}$ for all $r_1 \dots r_L \in S$.
- (c) $w_{i_1 \dots i_L}^{r_1 \dots r_L} = 0$ for all $r_1 \dots r_L \in S_0$.
- (d) For all $1 \leq r \leq m$ there is exactly one $1 \leq i_*^r \leq n_r$ such that $w_{i_*^r}^r = 1$.
- (e) For all $\{r_1, \dots, r_L\} \in \mathfrak{P}$ there is exactly one $i_1^* \dots i_L^* \in S$ such that $w_{i_1^* \dots i_L^*}^{r_1 \dots r_L} = 1$.

(We note in advance that property (d) will be crucial in the proof of Theorem 9.) Let $\mathcal{W} = \{ \vec{w}_\vartheta \}_{\vartheta \in \Theta}$ denote the set of vertices of $\varphi(M, S)$.

Again, $\varphi(M, S)$ is the space of theoretically possible states; and it may be that the empirically determined possible states of the system for different physical preparations constitute only a subset of $\varphi(M, S)$. In the absence of such an empirical restriction, for the sake of generality, in what follows we assume that the space of possible states is the whole $\varphi(M, S)$.

A closed convex polytope like $\varphi(M, S) \subset \mathbb{R}^{M+|S|}$ is a $\dim(\varphi(M, S))$ -dimensional manifold with boundary. Any coordinate system in the affine hull of $\varphi(M, S)$ can be a natural coordination of $\varphi(M, S)$.

Thus, $\varphi(M, S)$ as a manifold with boundary is a perfect mathematical representation of the states of the system; in fact, it is the most straightforward one, expressible directly in empirical terms. This is however not the only one. As Hardy puts it in the above quotation, the state of the system can be represented by “any mathematical object that can be used to determine the probability associated with the outcomes of any measurement”. For example, for our later purposes the convex decomposition

$$\vec{Z} = \sum_{\vartheta \in \Theta} \lambda_{\vartheta} \vec{w}_{\vartheta} \quad \lambda_{\vartheta} \geq 0, \sum_{\vartheta \in \Theta} \lambda_{\vartheta} = 1 \quad (68)$$

will be a more suitable characterization of a point of the state space. However, in general, this decomposition is not unique. In fact there are continuum many ways of such decomposition for all $\vec{Z} \in \text{Int } \varphi(M, S)$; and a unique one if \vec{Z} is on the boundary. As we will show, there are various good solutions for obtaining a unique representation of states in terms of their vertex decomposition (68).

Introduce the following notation: $\vec{\lambda} = (\lambda_{\vartheta})_{\vartheta \in \Theta} \in \mathbb{R}^{|\Theta|}$. Let

$$\Lambda = \left\{ \vec{\lambda} \in \mathbb{R}^{|\Theta|} \left| \lambda_{\vartheta} \geq 0, \sum_{\vartheta \in \Theta} \lambda_{\vartheta} = 1 \right. \right\}$$

Λ is the $(|\Theta| - 1)$ -dimensional standard simplex in $\mathbb{R}^{|\Theta|}$. Obviously,

$$D : \Lambda \rightarrow \varphi(M, S); \quad D(\vec{\lambda}) = \sum_{\vartheta \in \Theta} \lambda_{\vartheta} \vec{w}_{\vartheta} \quad (69)$$

is a continuous projection, and it preserves convex combination.

Lemma 5. *For all $\vec{Z} \in \varphi(M, S)$, $D^{-1}(\vec{Z})$ is a polytope contained in Λ .*

Proof. To satisfy (68), beyond being contained in Λ , $\vec{\lambda}$ has to satisfy the following system of linear equations:

$$\sum_{\vartheta \in \Theta} \lambda_{\vartheta} w_{\vartheta i}^r = Z_i^r \quad r \in I^M \quad (70)$$

$$\sum_{\vartheta \in \Theta} \lambda_{\vartheta} w_{i_1 \dots i_L}^{r_1 \dots r_L} = Z_{i_1 \dots i_L}^{r_1 \dots r_L} \quad r_1 \dots r_L \in S \quad (71)$$

For a given \vec{Z} , the set of solutions constitute an affine subspace $\mathfrak{a}_{\vec{Z}} \subset \mathbb{R}^{|\Theta|}$ with difference space $\mathfrak{B} \subset \mathbb{R}^{|\Theta|}$ constituted by the solutions of the homogeneous equations

$$\begin{aligned} \sum_{\vartheta \in \Theta} \lambda_{\vartheta} w_{\vartheta i}^r &= 0 & r &\in I^M \\ \sum_{\vartheta \in \Theta} \lambda_{\vartheta} w_{i_1 \dots i_L}^{r_1 \dots r_L} &= 0 & r_1 \dots r_L &\in S \end{aligned}$$

Notice that $D^{-1}(\vec{Z}) = \Lambda \cap \mathfrak{a}_{\vec{Z}}$. Due to the fact that an intersection of a polytope with an affine subspace is a polytope (Henk *et al.* 2004), each $D^{-1}(\vec{Z})$ is a polytope contained in Λ . \square

Lemma 6. $D^{-1}(\vec{Z})$, as a subset of $\mathbb{R}^{|\Theta|}$, continuously depends on \vec{Z} in the following sense:

$$\lim_{\vec{Z}' \rightarrow \vec{Z}} \max_{\vec{\lambda} \in D^{-1}(\vec{Z})} d(\vec{\lambda}, D^{-1}(\vec{Z}')) = 0 \quad (72)$$

$$\lim_{\vec{Z}' \rightarrow \vec{Z}} \max_{\vec{\lambda} \in D^{-1}(\vec{Z}')} d(\vec{\lambda}, D^{-1}(\vec{Z})) = 0 \quad (73)$$

where $d(\cdot, \cdot)$ denotes the usual distance of a point from a set.

Proof. We have to show that (72)–(73) hold approaching from all possible directions to \vec{Z} . In other words, if $t \in [0, 1]$ and $\Delta\vec{Z} \in \mathbb{R}^{M+|S|}$ is an arbitrary non-zero vector such that $\vec{Z} - \Delta\vec{Z} \in \varphi(M, S)$, then

$$\lim_{t \rightarrow 0} \max_{\vec{\lambda} \in D^{-1}(\vec{Z})} d(\vec{\lambda}, D^{-1}(\vec{Z} - t\Delta\vec{Z})) = 0 \quad (74)$$

$$\lim_{t \rightarrow 0} \max_{\vec{\lambda} \in D^{-1}(\vec{Z} - t\Delta\vec{Z})} d(\vec{\lambda}, D^{-1}(\vec{Z})) = 0 \quad (75)$$

Let $\Delta\vec{\lambda}$ be a solution of equations (70)–(71) with $\Delta\vec{Z}$:

$$\sum_{\vartheta \in \Theta} \Delta\lambda_{\vartheta} w_{\vartheta_i}^r = \Delta Z_i^r \quad r_i \in I^M \quad (76)$$

$$\sum_{\vartheta \in \Theta} \Delta\lambda_{\vartheta} w_{\vartheta_{i_1 \dots i_L}^{r_1 \dots r_L}} = \Delta Z_{i_1 \dots i_L}^{r_1 \dots r_L} \quad i_1 \dots i_L \in S \quad (77)$$

$\Delta\vec{\lambda}$ can be orthogonally decomposed as follows:

$$\Delta\vec{\lambda} = \Delta\vec{\lambda}^{\perp} + \Delta\vec{\lambda}^{\parallel} \quad \Delta\vec{\lambda}^{\perp} \in \mathcal{B}^{\perp} \text{ and } \Delta\vec{\lambda}^{\parallel} \in \mathcal{B}$$

Obviously, $\Delta\vec{\lambda}^{\perp}$ is uniquely determined by $\Delta\vec{Z}$; accordingly, replacing $\Delta\vec{Z}$ with $t\Delta\vec{Z}$ on the right hand side of (76)–(77) we get $t\Delta\vec{\lambda}^{\perp}$ in place of $\Delta\vec{\lambda}^{\perp}$. Notice that $|t\Delta\vec{\lambda}^{\perp}|$ is the distance between the affine subspaces of solutions $\mathfrak{a}_{\vec{Z}}$ and $\mathfrak{a}_{\vec{Z} - t\Delta\vec{Z}}$; tending to zero if $t \rightarrow 0$.

Let $\vec{\lambda}$ be an arbitrary point in $D^{-1}(\vec{Z})$ and let $\vec{\lambda}'$ be the point in $D^{-1}(\vec{Z} - \Delta\vec{Z})$ closest to $\vec{\lambda}$, that is,

$$d(\vec{\lambda}, D^{-1}(\vec{Z} - \Delta\vec{Z})) = |\vec{\lambda}' - \vec{\lambda}|$$

Consider the point

$$\vec{\lambda}_t = \vec{\lambda} + t(\vec{\lambda}' - \vec{\lambda})$$

Obviously, $\vec{\lambda}_t \in \Lambda$ and $\vec{\lambda}_t \in \mathfrak{a}_{\vec{Z}-t\Delta\vec{Z}}$ for all $t \in [0, 1]$, that is,

$$\vec{\lambda}_t \in D^{-1}(\vec{Z} - t\Delta\vec{Z})$$

Therefore,

$$d(\vec{\lambda}, D^{-1}(\vec{Z} - t\Delta\vec{Z})) \leq t|\vec{\lambda}' - \vec{\lambda}|$$

which implies (74).

Also, notice that

$$\lim_{t \rightarrow 0} \max_{\vec{\lambda} \in D^{-1}(\vec{Z} - t\Delta\vec{Z})} d(\vec{\lambda}, \mathfrak{a}_{\vec{Z}}) = 0$$

which implies (75), otherwise there would exist a convergent sequence of points from different $D^{-1}(\vec{Z} - t\Delta\vec{Z})$ sets such that the limiting point is not contained in $D^{-1}(\vec{Z})$, contradicting to the facts that Λ is closed and $D^{-1}(\vec{Z}) = \Lambda \cap \mathfrak{a}_{\vec{Z}}$. \square

Lemma 5 and 6 mean that the states of the system can be represented in a continuous way by a disjoint family of polytopes contained in Λ . This is of course a very unusual and inconvenient way of representation. However, we can easily make it more convenient by assigning a point in each $D^{-1}(\vec{Z})$ representing the entire polytope. There are several possibilities: for example, the center of mass, or any other notion of the center of a polytope. Here we will use the notion of the point of maximal entropy, which is perhaps physically also meaningful (Pitowsky 1989, p. 47).

The point of maximal entropy of an arbitrary polytope $\mathcal{S} \subset \Lambda$:

$$\vec{c}(\mathcal{S}) = \begin{cases} \text{maximize} & H(\vec{\lambda}) = -\sum_{\vartheta \in \Theta} \lambda_{\vartheta} \log \lambda_{\vartheta} \\ \text{subject to} & \vec{\lambda} \in \mathcal{S} \end{cases}$$

Since \mathcal{S} is contained in Λ , this maximization problem always has a solution. Meaning that $\vec{c}(\mathcal{S})$ is uniquely determined and always contained in \mathcal{S} .

Lemma 7. *Let us define the following section of the bundle projection (69):*

$$\begin{aligned} \sigma : \varphi(M, S) &\rightarrow \Lambda \\ \sigma(\vec{Z}) &= \vec{c}(D^{-1}(\vec{Z})) \in D^{-1}(\vec{Z}) \end{aligned} \quad (78)$$

Then, $\sigma(\vec{Z})$ is continuous in \vec{Z} , that is, for all $\vec{Z}, \vec{Z}' \in \varphi(M, S)$,

$$\lim_{\vec{Z}' \rightarrow \vec{Z}} \sigma(\vec{Z}') = \sigma(\vec{Z})$$

Proof. Consider a sufficiently fine division of the unit cube $C^{|\Theta|} \subset \mathbb{R}^{|\Theta|}$ into equally sized small cubes of volume ΔV . Denote the i -th such elementary cube by C_i . The point of maximal entropy of a polytope $\mathcal{S} \subset \Lambda \subset C^{|\Theta|}$ can be approximated with arbitrary precision in the following way:

$$\vec{c}(\mathcal{S}) \simeq \begin{cases} \text{maximize} & H(\vec{\lambda}) = -\sum_{\theta \in \Theta} \lambda_\theta \log \lambda_\theta \\ \text{subject to} & i \in \{j \mid \mathcal{S} \cap C_j \neq \emptyset\} \end{cases} \quad (79)$$

where $\vec{\lambda}$ is, say, the center of C_i . Due to Lemma 6, for all $\Delta V > 0$ there is an $\varepsilon > 0$ such that, for all elementary cube C_i ,

$$D^{-1}(\vec{Z}') \cap C_i \neq \emptyset \Leftrightarrow D^{-1}(\vec{Z}) \cap C_i \neq \emptyset \quad \text{if } |\vec{Z}' - \vec{Z}| < \varepsilon$$

Meaning that, for a sufficiently small ε , approximation (79) leads to the same result for $D^{-1}(\vec{Z}')$ and $D^{-1}(\vec{Z})$. Therefore,

$$\lim_{\vec{Z}' \rightarrow \vec{Z}} \vec{c}(D^{-1}(\vec{Z}')) = \vec{c}(D^{-1}(\vec{Z}))$$

□

By means of σ (or any similar continuous section) the whole state space $\varphi(M, S)$ can be lifted into a $\dim(\varphi(M, S))$ -dimensional submanifold with boundary:

$$\Lambda_\sigma = \sigma(\varphi(M, S)) \subset \Lambda \quad (80)$$

4 Dynamics

So far, nothing has been said about the dynamics of the system, that is, about the time evolution of the state \vec{Z} . First we have to introduce the concept of time evolution in general operational terms. Let us start with the most general case.

Imagine that the system is in state $\vec{Z}(t_0)$ after a certain physical preparation at time t_0 . According to the definition of state, this means that the system responds to the various measurement operations right after time t_0 in a way described in (16)–(17). Let then the system evolve under a given set of circumstances until time t . Let $\vec{Z}(t)$ be the system's state at moment t . Again, this means that the system responds to the various measurement operations right after time t in a way described in (16)–(17) with $\vec{Z}(t)$. Thus, we have a temporal path of the system in the space of states $\varphi(M, S)$. It is quite plausible to assume that $\vec{Z}(t)$ is a continuous curve in $\varphi(M, S)$. By means of a continuous cross section like (78), $\vec{Z}(t)$ can be lifted and expressed as $\sigma(\vec{Z}(t))$, a continuous curve on Λ_σ .

Whether the time evolution of the system shows any regularity whatsoever, is a matter of empirical facts reflected in the observed relative frequencies under

various circumstances. Next, as an empirically observed regularity, we assume a typical situation when the time evolution $\vec{Z}(t)$ can be generated by a one-parameter group of transformations of $\varphi(M, S)$.

(E4) The time evolutions of states are such that there exists a one-parameter group of transformations of $\varphi(M, S)$, F_t , satisfying the following conditions:

$$F_t : \varphi(M, S) \rightarrow \varphi(M, S) \text{ is one-to-one}$$

$$F : \mathbb{R} \times \varphi(M, S) \rightarrow \varphi(M, S); \left(t, \vec{Z}\right) \mapsto F_t\left(\vec{Z}\right) \text{ is continuous}$$

$$F_{t+s} = F_s \circ F_t$$

$$F_{-t} = F_t^{-1}; \text{ consequently, } F_0 = id_{\varphi(M, S)}$$

and the time evolution of an arbitrary initial state $\vec{Z}(t_0) \in \varphi(M, S)$ is $\vec{Z}(t) = F_{t-t_0}\left(\vec{Z}(t_0)\right)$.

It is worth mentioning that though the state space $\varphi(M, S)$ is closed under convex combination, the stipulated empirical facts do not imply that F_t should preserve convex combinations.

By means of the continuous cross section (78), F_t generates a one-parameter group of transformations on Λ_σ , $K_t = \sigma \circ F_t \circ D$, with exactly the same properties:

$$K_t : \Lambda_\sigma \rightarrow \Lambda_\sigma \text{ is one-to-one}$$

$$K : \mathbb{R} \times \Lambda_\sigma \rightarrow \Lambda_\sigma; \left(t, \vec{Z}\right) \mapsto K_t\left(\vec{Z}\right) \text{ is continuous}$$

$$K_{t+s} = K_s \circ K_t$$

$$K_{-t} = K_t^{-1}; \text{ consequently, } K_0 = id_{\Lambda_\sigma}$$

5 Ontology

Thus, the state of the system $\vec{Z} \in \varphi(M, S)$, together with its time evolution, completely characterizes the system's probabilistic behavior in the sense of Theorem 1. In general, such a probabilistic description can admit different underlying ontological pictures. Though, as we will see, some of those underlying ontologies imply further conditions on the observed relative frequencies. We will mention three important cases, but various combinations are conceivable.

Case 1 In the most general case, without any further restriction on the observed relative frequencies, the outcomes of the measurements are random events produced in the measurement process itself. The state \vec{Z} characterizes the system in a dispositional sense: the system has a propensity to behave in a certain way, that is, to produce a certain statistics of outcomes, if a given combination

of measurements is performed. In general, the produced statistics is such that, for example,

$$\pi(X_i^r | a_r \wedge a_{r'}) \neq \pi(X_i^r | a_r) \quad \{r, r'\} \in \mathfrak{P} \quad (81)$$

meaning that the underlying process is “contextual” in the sense that the system’s statistical behavior against measurement a_r can be influenced by the performance of another measurement $a_{r'}$.

Case 2 In the second case we assume that there is no such cross-influence in the underlying ontology. That is, the observed relative frequencies satisfy the following general condition:

$$\begin{aligned} & \pi\left(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L} \wedge a_{r'_1} \wedge \dots \wedge a_{r'_{L'}}\right) \\ &= \pi\left(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L}\right) \end{aligned} \quad (82)$$

for all $L, L', 2 \leq L + L' \leq m$, $\frac{r_1 \dots r_L}{i_1 \dots i_L} \in S$, and $\{r_1, \dots, r_L, r'_1, \dots, r'_{L'}\} \in \mathfrak{P}$. This does not mean that there cannot be correlation between the outcomes $X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L}$ and the performance of measurement $a_{r'_1} \wedge \dots \wedge a_{r'_{L'}}$. It only means that the correlation must be the consequence of the fact that the measurement operations $a_{r'_1} \wedge \dots \wedge a_{r'_{L'}}$ and $a_{r_1} \wedge \dots \wedge a_{r_L}$ are correlated; $a_{r_1} \wedge \dots \wedge a_{r_L}$ must be the common cause responsible for the correlation. Indeed, (82) is equivalent with the following “screening off” condition:

$$\begin{aligned} & \pi\left(a_{r'_1} \wedge \dots \wedge a_{r'_{L'}} \wedge X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L}\right) \\ &= \pi\left(a_{r'_1} \wedge \dots \wedge a_{r'_{L'}} | a_{r_1} \wedge \dots \wedge a_{r_L}\right) \\ & \quad \times \pi\left(X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L}\right) \end{aligned} \quad (83)$$

for all $L, L', 2 \leq L + L' \leq m$, $\frac{r_1 \dots r_L}{i_1 \dots i_L} \in S$, and $\{r_1, \dots, r_L, r'_1, \dots, r'_{L'}\} \in \mathfrak{P}$.

All this means that the state of the system \vec{Z} reflects the propensities of the system to produce a certain statistics of outcomes against each possible measurement/measurement combination, separately. The observed statistics reveals the propensity in question, but, in general, we are not entitled to say that a single outcome (of a measurement/measurement combination) reveals an element of reality existing independently of the measurement(s). As we will see below, that would require a stronger restriction on the observed frequencies.

Case 3 Assume that the underlying ontology contains such elements of reality. Let us denote them by $\#X_i^r$ ($i \in I^M$). More precisely, let $\#X_i^r$ denote the event that the element of reality revealed in the outcome X_i^r is present in the given run of the experiment. Certainly, every such event $\#X_i^r$, even if hidden to us, must have some relative frequency. That is to say, there must exist a relative frequency function π' on the extended free Boolean algebra \mathcal{A}' generated by the set

$$G' = \{a_r\}_{r=1,2,\dots,m} \cup \{X_i^r\}_{i \in I^M} \cup \{\#X_j^s\}_{j \in I^M} \quad (84)$$

such that

$$\pi' \big|_{\mathcal{A} \subset \mathcal{A}'} = \pi \quad (85)$$

The ontological assumption that $\#X_i^r$ is revealed by the measurement outcome X_i^r means that

$$\pi' (X_i^r | a_r \wedge \#X_i^r) = 1 \quad (86)$$

$$\pi' (X_i^r | a_r \wedge \neg \#X_i^r) = 0 \quad (87)$$

$$\pi' (a_r \wedge \#X_i^r) = \pi' (a_r) \pi' (\#X_i^r) \quad (88)$$

Similarly,

$$\pi' (X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L} \wedge \#X_{i_1}^{r_1} \wedge \dots \wedge \#X_{i_L}^{r_L}) = 1 \quad (89)$$

$$\pi' (X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L} \wedge \neg (\#X_{i_1}^{r_1} \wedge \dots \wedge \#X_{i_L}^{r_L})) = 0 \quad (90)$$

$$\begin{aligned} \pi' (a_{r_1} \wedge \dots \wedge a_{r_L} \wedge \#X_{i_1}^{r_1} \wedge \dots \wedge \#X_{i_L}^{r_L}) &= \pi' (a_{r_1} \wedge \dots \wedge a_{r_L}) \\ &\times \pi' (\#X_{i_1}^{r_1} \wedge \dots \wedge \#X_{i_L}^{r_L}) \end{aligned} \quad (91)$$

for all $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix} \in S$.

Now, (86)–(91) and (85) imply that

$$\pi' (\#X_i^r) = \pi (X_i^r | a_r) = Z_i^r \quad (92)$$

$$\begin{aligned} \pi' (\#X_{i_1}^{r_1} \wedge \dots \wedge \#X_{i_L}^{r_L}) &= \pi (X_{i_1}^{r_1} \wedge \dots \wedge X_{i_L}^{r_L} | a_{r_1} \wedge \dots \wedge a_{r_L}) \\ &= Z_{i_1 \dots i_L}^{r_1 \dots r_L} \end{aligned} \quad (93)$$

for all $r_i \in I^M$ and $\begin{smallmatrix} r_1 \dots r_L \\ i_1 \dots i_L \end{smallmatrix} \in S$.

Notice that on the right hand side of (92)–(93) we have the components of \vec{Z} . At the same time, on the left hand side of (92)–(93) we have numbers that are values of relative frequencies. Therefore the components of \vec{Z} must constitute values of relative frequencies (of the occurrences of elements of reality $\#X_i^r$ and $\#X_{i_1}^{r_1} \dots \wedge \#X_{i_L}^{r_L}$). Since values of relative frequencies satisfy the Kolmogorovian laws of classical probability, \vec{Z} must be in the so-called classical correlation polytope (Pitowsky 1989, Ch. 2):

$$\vec{Z} \in c(M, S) \quad (94)$$

(Equivalently, the components of \vec{Z} must satisfy the corresponding Bell-type inequalities.) In this case the physical state of the system admits a more fine-grained characterization than the probabilistic description provided by \vec{Z} : in each run of the experiment the system can be thought of as being in an underlying physical state (fixing whether the elements of reality $\#X_i^r$ and $\#X_{i_1}^{r_1} \dots \wedge \#X_{i_L}^{r_L}$ are present or not) that predetermines the outcome of every possible measurement, given that the measurement in question is performed.

Thus, as we have seen from the above examples, the probabilistic–operational notion of state admits different underlying ontologies, depending on whether

some further conditions are met or not. Note that condition (82) in Case 2 is sometimes called “no-signaling condition”; and Case 3 is usually interpreted as “admitting deterministic non-contextual hidden variables”. In what follows, we do not assume anything more about the observed relative frequencies than we stipulated in **(E1)**–**(E3)**. Meaning that we remain within the most general framework of Case 1.

6 Quantum Representation

So far in the previous sections, we have stayed within the framework of classical Kolmogorovian probability theory; including the notion of state, which is a simple vector constructed from classical conditional probabilities. Meaning that any physical system—traditionally categorized as classical or quantum—that can be described in operational terms can be described within classical Kolmogorovian probability theory. It is worth pointing out that this is also the case when the system is traditionally described in terms of the Hilbert space quantum mechanical formalism. That is, all the empirically expressible content of the quantum mechanical description can be described in the language of classical Kolmogorovian probabilities; including what we refer to as “quantum probability”, given by the usual trace formula, which can be expressed simply as classical conditional probability. All this is in perfect alignment with the content of the so-called Kolmogorovian Censorship Hypothesis (Szabó 1995; Bana and Durt 1997; Szabó 2001; Rédei 2010; Hofer-Szabó *et al.* 2013, Ch. 9).

In the remainder of the paper we will show that the opposite is also true: anything that can be described in operational terms can be represented in the Hilbert space quantum mechanical formalism, if we wish. We will show that there always exists:

- (Q1) a suitable Hilbert space, such that
- (Q2) the outcomes of each measurement can be represented by a system of pairwise orthogonal closed subspaces, spanning the whole Hilbert space,
- (Q3) the states of the system can be represented by pure state operators with suitable state vectors, and
- (Q4) the probabilities of the measurement outcomes, with arbitrarily high precision, can be reproduced by the usual trace formula of quantum mechanics.

Moreover, in the case of real-valued quantities,

- (Q5) each quantity, if we wish, can be associated with a suitable self-adjoint operator, such that
- (Q6) in all states of the system, the expectation value of the quantity can be reproduced, with arbitrarily high precision, by the usual trace formula applied to the associated self-adjoint operator,

- (Q7) the possible measurement results are the eigenvalues of the operator,
(Q8) and the corresponding outcome events are represented by the eigenspaces pertaining to the eigenvalues respectively, according to the spectral decomposition of the operator in question.

In preparation for our quantum representation theorem, first we prove a lemma, which is a straightforward consequence of previous results in Pitowsky's *Quantum Probability – Quantum Logic*.

Lemma 8. *For each vector $\vec{f} \in l(M, S)$ there exists a Hilbert space ${}^{(\vec{f})}H$ and closed subspaces ${}^{(\vec{f})}E_i^r$ in the subspace lattice $L({}^{(\vec{f})}H)$ and a pure state $P_{\Psi_{\vec{f}}}$ with a suitable unit vector $\Psi_{\vec{f}} \in {}^{(\vec{f})}H$, such that*

$$f_i^r \simeq \text{tr} \left(P_{\Psi_{\vec{f}}} {}^{(\vec{f})}E_i^r \right) \quad (95)$$

$$f_{i_1 \dots i_L}^{r_1 \dots r_L} \simeq \text{tr} \left(P_{\Psi_{\vec{f}}} \left({}^{(\vec{f})}E_{i_1}^{r_1} \wedge \dots \wedge {}^{(\vec{f})}E_{i_L}^{r_L} \right) \right) \quad (96)$$

for all $r_i \in I^M$ and $r_{i_1 \dots i_L} \in S$.

Proof. It follows from a straightforward generalization of a theorem in (Pitowsky 1989, p. 65) that the so called quantum polytope $q(M, S)$, constituted by the vectors satisfying (95)–(96) with exact equality, is a dense convex subset of $l(M, S)$; it is essentially $l(M, S)$ save for some points on the boundary of $l(M, S)$, namely the finite number of non-classical vertices. $q(M, S)$ contains the interior of $l(M, S)$. This means that arbitrary vector $\vec{f} \in l(M, S)$ can be regarded as “an element of” $q(M, S)$ with arbitrary precision. That is, there exists a Hilbert space ${}^{(\vec{f})}H$ and for each $r_i \in I^M$ a closed subspace/projector ${}^{(\vec{f})}E_i^r$ in the subspace/projector lattice $L({}^{(\vec{f})}H)$ and a suitable unit vector $\Psi_{\vec{f}} \in {}^{(\vec{f})}H$, such that the approximate equalities (95)–(96) hold. \square

Theorem 9. *There exists a Hilbert space H and for each outcome event X_i^r a closed subspace/projector E_i^r in the subspace/projector lattice $L(H)$, such that for each state \vec{Z} of the system there exists a pure state $P_{\Psi_{\vec{Z}}}$ with a suitable unit vector $\Psi_{\vec{Z}} \in H$, such that*

$$Z_i^r \simeq \text{tr} \left(P_{\Psi_{\vec{Z}}} E_i^r \right) \quad (97)$$

$$Z_{i_1 \dots i_L}^{r_1 \dots r_L} \simeq \text{tr} \left(P_{\Psi_{\vec{Z}}} \left(E_{i_1}^{r_1} \wedge \dots \wedge E_{i_L}^{r_L} \right) \right) \quad (98)$$

and

$$E_i^r \perp E_j^r \quad i \neq j \quad (99)$$

$$\bigvee_{k=1}^{n_r} E_k^r = H \quad (100)$$

for all $r_i, r_j \in I^M$ and $r_{i_1 \dots i_L} \in S$.

Proof. The proof is essentially based on Lemma 4 and proceeds in two major steps.

Step I

Consider the vertices of $\varphi(M, S)$, $\{\vec{w}_\vartheta\}_{\vartheta \in \Theta}$. Each \vec{w}_ϑ is a vector in $l(M, S)$. Therefore, due to Lemma 8, for each \vec{w}_ϑ there exists a Hilbert space ${}^\vartheta\tilde{H}$ and closed subspaces ${}^\vartheta\tilde{E}_i^r$ in the subspace lattice $L({}^\vartheta\tilde{H})$ and a pure state $P_{\tilde{\Psi}_\vartheta}$ with a suitable unit vector $\tilde{\Psi}_\vartheta \in {}^\vartheta\tilde{H}$, such that

$$w_{\vartheta i}^r \simeq \text{tr}(P_{\tilde{\Psi}_\vartheta} {}^\vartheta\tilde{E}_i^r) \quad (101)$$

$$w_{\vartheta i_1 \dots i_L}^{r_1 \dots r_L} \simeq \text{tr}(P_{\tilde{\Psi}_\vartheta} ({}^\vartheta\tilde{E}_{i_1}^{r_1} \wedge \dots \wedge {}^\vartheta\tilde{E}_{i_L}^{r_L})) \quad (102)$$

for all $i \in I^M$ and $i_1 \dots i_L \in S$.

Now, let

$${}^\vartheta H = H^{n_1} \otimes H^{n_2} \otimes \dots \otimes H^{n_m} \otimes {}^\vartheta\tilde{H} \quad (103)$$

where $H^{n_1}, H^{n_2}, \dots, H^{n_m}$ are Hilbert spaces of dimension n_1, n_2, \dots, n_m . Let $e_1^r, e_2^r, \dots, e_{n_r}^r$ be an orthonormal basis in H^{n_r} . Define the corresponding subspace for each event X_i^r as follows:

$${}^\vartheta E_i^r = H^{n_1} \otimes \dots \otimes H^{n_{r-1}} \otimes [e_i^r] \otimes H^{n_{r+1}} \dots \otimes H^{n_m} \otimes {}^\vartheta\tilde{E}_i^r \quad (104)$$

where $[e_i^r]$ stands for the one-dimensional subspace spanned by e_i^r in H^{n_r} . Notice that, for all r ,

$${}^\vartheta E_i^r \perp {}^\vartheta E_j^r \quad \text{if } i \neq j \quad (105)$$

due to the fact that $e_1^r, e_2^r, \dots, e_{n_r}^r$ is an orthonormal basis in H^{n_r} .

Due to Lemma 4, for all $1 \leq r \leq m$ there is exactly one $1 \leq i_*^r \leq n_r$ such that $w_{\vartheta i_*^r}^r = 1$. This makes it possible to define the state vector in ${}^\vartheta H$ as the following unit vector:

$$\Psi_\vartheta = e_{\vartheta i_*^1}^1 \otimes e_{\vartheta i_*^2}^2 \otimes \dots \otimes e_{\vartheta i_*^r}^r \otimes \dots \otimes e_{\vartheta i_*^m}^m \otimes \tilde{\Psi}_\vartheta$$

Now, it is easily verifiable that

$$w_{\vartheta i}^r \simeq \text{tr}(P_{\Psi_\vartheta} {}^\vartheta E_i^r) \quad (106)$$

$$w_{\vartheta i_1 \dots i_L}^{r_1 \dots r_L} \simeq \text{tr}(P_{\Psi_\vartheta} ({}^\vartheta E_{i_1}^{r_1} \wedge \dots \wedge {}^\vartheta E_{i_L}^{r_L})) \quad (107)$$

for all $i \in I^M$, $i_1 \dots i_L \in S$, and for all $\vartheta \in \Theta$. For example:

If $w_{\vartheta i}^r = 1$, and so $i = i_*^r$, then

$$\begin{aligned} \text{tr}(P_{\Psi_\vartheta} {}^\vartheta E_i^r) &= \underbrace{\text{tr}(P_{e_{\vartheta i_*^1}^1} H^{n_1})}_1 \text{tr}(P_{e_{\vartheta i_*^2}^2} H^{n_2}) \dots \text{tr}(P_{e_{\vartheta i_*^r}^r} [e_{\vartheta i_*^r}^r]) \dots \\ &\quad \text{tr}(P_{e_{\vartheta i_*^m}^m} H^{n_m}) \underbrace{\text{tr}(P_{\tilde{\Psi}_\vartheta} {}^\vartheta\tilde{E}_i^r)}_{\simeq w_{\vartheta i}^r = 1} \simeq 1 \end{aligned}$$

If $w_{\vartheta_i^r} = 0$, and so $i \neq \vartheta_{i_*}^r$, then

$$\begin{aligned} \text{tr} (P_{\Psi_\vartheta} \vartheta E_i^r) &= \underbrace{\text{tr} \left(P_{e_{\vartheta_{i_*}^1}^1} H^{n_1} \right)}_1 \text{tr} \left(P_{e_{\vartheta_{i_*}^2}^2} H^{n_2} \right) \dots \text{tr} \left(P_{e_{\vartheta_{i_*}^r}^r} \left[e_{i \neq \vartheta_{i_*}^r}^r \right] \right) \dots \\ &\quad \text{tr} \left(P_{e_{\vartheta_{i_*}^m}^m} H^{n_m} \right) \underbrace{\text{tr} \left(P_{\Psi_\vartheta} \vartheta \tilde{E}_i^r \right)}_{\simeq w_{\vartheta_i^r} = 0} = 0 \end{aligned}$$

Similarly, if $w_{\vartheta_{i_1}^{r_1}} = 0$, $w_{\vartheta_{i_2}^{r_2}} = 1$ then

$$\begin{aligned} \text{tr} (P_{\Psi_\vartheta} (\vartheta E_{i_1}^{r_1} \wedge \vartheta E_{i_2}^{r_2})) &= \text{tr} \left(P_{e_{\vartheta_{i_*}^1}^1} (H^{n_1} \wedge H^{n_1}) \right) \dots \\ &\quad \underbrace{\text{tr} \left(P_{e_{\vartheta_{i_*}^{r_1}}^{r_1}} \left(\left[e_{i_1 \neq \vartheta_{i_*}^{r_1}}^{r_1} \right] \wedge H^{n_{r_1}} \right) \right)}_0 \dots \underbrace{\text{tr} \left(P_{e_{i_*}^{r_2}}^{r_2} \left(H^{n_{r_2}} \wedge \left[e_{i_2 = \vartheta_{i_*}^{r_2}}^{r_2} \right] \right) \right)}_1 \dots \\ &\quad \text{tr} \left(P_{e_{\vartheta_{i_*}^m}^m} (H^{n_m} \wedge H^{n_m}) \right) \underbrace{\text{tr} \left(P_{\Psi_\vartheta} (\vartheta \tilde{E}_{i_1}^{r_1} \wedge \vartheta \tilde{E}_{i_2}^{r_2}) \right)}_{\simeq w_{\vartheta_{i_1 i_2}^{r_1 r_2}} = 0} = 0 \end{aligned}$$

in accordance with that $\vartheta w_{i_1 i_2}^{r_1 r_2}$ must be equal to 0, due to (37).

If $w_{\vartheta_{i_1}^{r_1}} = 1$, $w_{\vartheta_{i_2}^{r_2}} = 1$ then

$$\begin{aligned} \text{tr} (P_{\Psi_\vartheta} (\vartheta E_{i_1}^{r_1} \wedge \vartheta E_{i_2}^{r_2})) &= \text{tr} \left(P_{e_{\vartheta_{i_*}^1}^1} (H^{n_1} \wedge H^{n_1}) \right) \dots \\ &\quad \underbrace{\text{tr} \left(P_{e_{\vartheta_{i_*}^{r_1}}^{r_1}} \left(\left[e_{i_1 = \vartheta_{i_*}^{r_1}}^{r_1} \right] \wedge H^{n_{r_1}} \right) \right)}_1 \dots \underbrace{\text{tr} \left(P_{e_{i_*}^{r_2}}^{r_2} \left(H^{n_{r_2}} \wedge \left[e_{i_2 = \vartheta_{i_*}^{r_2}}^{r_2} \right] \right) \right)}_1 \dots \\ &\quad \text{tr} \left(P_{e_{\vartheta_{i_*}^m}^m} (H^{n_m} \wedge H^{n_m}) \right) \underbrace{\text{tr} \left(P_{\Psi_\vartheta} (\vartheta \tilde{E}_{i_1}^{r_1} \wedge \vartheta \tilde{E}_{i_2}^{r_2}) \right)}_{\simeq w_{\vartheta_{i_1 i_2}^{r_1 r_2}}} \simeq w_{\vartheta_{i_1 i_2}^{r_1 r_2}} \end{aligned}$$

Step II

Consider an arbitrary state \vec{Z} . Since $\vec{Z} \in \varphi(M, S)$, it can be decomposed in terms of the vertices $\{\vec{w}_\vartheta\}_{\vartheta \in \Theta}$ in the fashion of (68) with some coefficients $\{\lambda_\vartheta\}_{\vartheta \in \Theta}$.

Now we construct the Hilbert space H and the state vector $\Psi_{\vec{Z}}$:

$$H = \bigoplus_{\vartheta \in \Theta} \vartheta H \quad (108)$$

$$\Psi_{\bar{Z}} = \bigoplus_{\vartheta \in \Theta} \sqrt{\lambda_{\vartheta}} \Psi_{\vartheta} \quad (109)$$

Obviously,

$$\langle \Psi_{\bar{Z}}, \Psi_{\bar{Z}} \rangle = \sum_{\vartheta \in \Theta} \lambda_{\vartheta} \langle \Psi_{\vartheta}, \Psi_{\vartheta} \rangle = 1$$

The subspaces E_i^r representing the outcome events will be defined further below. First we consider the following subspaces of H :

$${}^*E_i^r = \bigoplus_{\vartheta \in \Theta} {}^{\vartheta}E_i^r$$

Since

$$\begin{aligned} \text{tr}(P_{\Psi_{\bar{Z}}} {}^*E_i^r) &= \langle \Psi_{\bar{Z}}, {}^*E_i^r \Psi_{\bar{Z}} \rangle = \sum_{\vartheta \in \Theta} \langle \sqrt{\lambda_{\vartheta}} \Psi_{\vartheta}, {}^{\vartheta}E_i^r \sqrt{\lambda_{\vartheta}} \Psi_{\vartheta} \rangle \\ &= \sum_{\vartheta \in \Theta} \lambda_{\vartheta} \text{tr}(P_{\Psi_{\vartheta}} {}^{\vartheta}E_i^r) \end{aligned}$$

$$\begin{aligned} \text{tr}(P_{\Psi_{\bar{Z}}} ({}^*E_{i_1}^{r_1} \wedge \dots \wedge {}^*E_{i_L}^{r_L})) &= \langle \Psi_{\bar{Z}}, ({}^*E_{i_1}^{r_1} \wedge \dots \wedge {}^*E_{i_L}^{r_L}) \Psi_{\bar{Z}} \rangle \\ &= \sum_{\vartheta \in \Theta} \langle \sqrt{\lambda_{\vartheta}} \Psi_{\vartheta}, ({}^{\vartheta}E_{i_1}^{r_1} \wedge \dots \wedge {}^{\vartheta}E_{i_L}^{r_L}) \sqrt{\lambda_{\vartheta}} \Psi_{\vartheta} \rangle \\ &= \sum_{\vartheta \in \Theta} \lambda_{\vartheta} \text{tr}(P_{\Psi_{\vartheta}} ({}^{\vartheta}E_{i_1}^{r_1} \wedge \dots \wedge {}^{\vartheta}E_{i_L}^{r_L})) \end{aligned}$$

from (106)–(107) and (68) we have

$$Z_i^r \simeq \text{tr}(P_{\Psi_{\bar{Z}}} {}^*E_i^r) \quad (110)$$

$$Z_{i_1 \dots i_L}^{r_1 \dots r_L} \simeq \text{tr}(P_{\Psi_{\bar{Z}}} ({}^*E_{i_1}^{r_1} \wedge \dots \wedge {}^*E_{i_L}^{r_L})) \quad (111)$$

Also, as direct sum preserves orthogonality, from (105) we have

$${}^*E_i^r \perp {}^*E_j^r \quad \text{if } i \neq j \quad (112)$$

For all $1 \leq r \leq m$, let ${}^*E_{i_0}^r \in \{{}^*E_1^r, {}^*E_2^r, \dots, {}^*E_{n_r}^r\}$ be arbitrarily chosen, and let ${}^*E_{\perp}^r = \left(\bigvee_{i=1}^{n_r} {}^*E_i^r \right)^{\perp} = \bigwedge_{i=1}^{n_r} ({}^*E_i^r)^{\perp}$. We define the subspaces representing the outcome events as follows:

$$E_i^r = \begin{cases} {}^*E_i^r & i \neq i_0 \\ {}^*E_{i_0}^r \vee {}^*E_{\perp}^r & i = i_0 \end{cases} \quad (113)$$

Obviously, (112) implies ${}^*E_{i_0}^r \leq \bigwedge_{i \neq i_0} ({}^*E_i^r)^{\perp}$. Due to the orthomodularity of the subspace lattice $L(H)$, we have

$${}^*E_{i_0}^r \vee \left(\underbrace{({}^*E_{i_0}^r)^{\perp} \wedge \left(\bigwedge_{i \neq i_0} ({}^*E_i^r)^{\perp} \right)}_{{}^*E_{\perp}^r} \right) = \bigwedge_{i \neq i_0} ({}^*E_i^r)^{\perp}$$

meaning that

$$E_{i_0}^r = \bigwedge_{i \neq i_0} (*E_i^r)^\perp$$

Therefore, taking into account (112) and (113),

$$E_i^r \perp E_j^r \quad \text{if } i \neq j \quad (114)$$

Also, it is obviously true that

$$\bigvee_{i=1}^{n_r} E_i^r = H \quad (115)$$

Both (114) and (115) hold for all $1 \leq r \leq m$. There remains to show (97)–(98).

It follows from (113) that

$$E_i^r \geq *E_i^r$$

for all $r \in I^M$. Similarly,

$$E_{i_1}^{r_1} \wedge \dots \wedge E_{i_L}^{r_L} \geq *E_{i_1}^{r_1} \wedge \dots \wedge *E_{i_L}^{r_L}$$

for all $\vec{r}_{i_1 \dots i_L} \in S$. Therefore, for all $\vec{Z} \in \varphi(M, S)$,

$$\langle \Psi_{\vec{Z}}, E_i^r \Psi_{\vec{Z}} \rangle \geq \langle \Psi_{\vec{Z}}, *E_i^r \Psi_{\vec{Z}} \rangle \quad (116)$$

and

$$\langle \Psi_{\vec{Z}}, E_{i_1}^{r_1} \wedge \dots \wedge E_{i_L}^{r_L} \Psi_{\vec{Z}} \rangle \geq \langle \Psi_{\vec{Z}}, *E_{i_1}^{r_1} \wedge \dots \wedge *E_{i_L}^{r_L} \Psi_{\vec{Z}} \rangle \quad (117)$$

Now, (10) and (110) imply that

$$\sum_{\substack{i \\ (r \in I^M)}} \langle \Psi_{\vec{Z}}, *E_i^r \Psi_{\vec{Z}} \rangle \simeq 1$$

At the same time, taking into account (114)–(115), we have

$$1 = \sum_{\substack{i \\ (r \in I^M)}} \langle \Psi_{\vec{Z}}, E_i^r \Psi_{\vec{Z}} \rangle \geq \sum_{\substack{i \\ (r \in I^M)}} \langle \Psi_{\vec{Z}}, *E_i^r \Psi_{\vec{Z}} \rangle \simeq 1 \quad (118)$$

From (116) and (118), therefore,

$$\text{tr}(P_{\Psi_{\vec{Z}}} E_i^r) \simeq \text{tr}(P_{\Psi_{\vec{Z}}} *E_i^r) \quad (119)$$

Similarly, on the one hand, (11) and (111) imply that

$$\sum_{\substack{i_1, i_2 \dots i_L \\ (r_1 \dots r_L \in S)}} \langle \Psi_{\vec{Z}}, *E_{i_1}^{r_1} \wedge \dots \wedge *E_{i_L}^{r_L} \Psi_{\vec{Z}} \rangle \simeq 1 \quad (120)$$

On the other hand, $\{E_{i_1}^{r_1} \wedge \dots \wedge E_{i_L}^{r_L}\}_{\substack{i_1, i_2 \dots i_L \\ (r_1 \dots r_L \in S)}}$ is an orthogonal system of subspaces. Therefore,

$$\begin{aligned} 1 &\geq \sum_{\substack{i_1, i_2 \dots i_L \\ (r_1 \dots r_L \in S)}} \langle \Psi_{\bar{Z}}, E_{i_1}^{r_1} \wedge \dots \wedge E_{i_L}^{r_L} \Psi_{\bar{Z}} \rangle \\ &\geq \sum_{\substack{i_1, i_2 \dots i_L \\ (r_1 \dots r_L \in S)}} \langle \Psi_{\bar{Z}}, {}^*E_{i_1}^{r_1} \wedge \dots \wedge {}^*E_{i_L}^{r_L} \Psi_{\bar{Z}} \rangle \simeq 1 \end{aligned} \quad (121)$$

From (117) and (121), for all $\substack{r_1 \dots r_L \\ i_1 \dots i_L} \in S$, we have

$$\text{tr} (P_{\Psi_{\bar{Z}}} E_{i_1}^{r_1} \wedge \dots \wedge E_{i_L}^{r_L}) \simeq \text{tr} (P_{\Psi_{\bar{Z}}} {}^*E_{i_1}^{r_1} \wedge \dots \wedge {}^*E_{i_L}^{r_L}) \quad (122)$$

Thus, (110)–(111) together with (119) and (122) imply (97)–(98). \square

With Theorem 9 we have accomplished (Q1)–(Q4). The next two theorems cover statements (Q5)–(Q8).

Theorem 10. *Let a_r be the measurement of a real valued quantity with labeling (12). On the Hilbert space H , there exists a self-adjoint operator A_r such that for every state of the system \bar{Z} ,*

$$\langle \alpha_r \rangle_{\bar{Z}} \simeq \text{tr} (P_{\Psi_{\bar{Z}}} A_r) \quad (123)$$

Proof. Let

$$A_r = \sum_{i=1}^{n_r} \alpha_i^r E_i^r \quad (124)$$

A_r is obviously a self-adjoint operator, and

$$\begin{aligned} \langle \alpha_r \rangle_{\bar{Z}} &= \sum_{i=1}^{n_r} \alpha_i^r \pi (X_i^r | a_r) = \sum_{i=1}^{n_r} \alpha_i^r Z_i^r \simeq \sum_{i=1}^{n_r} \alpha_i^r \text{tr} (P_{\Psi_{\bar{Z}}} E_i^r) \\ &= \text{tr} \left(P_{\Psi_{\bar{Z}}} \sum_{i=1}^{n_r} \alpha_i^r E_i^r \right) = \text{tr} (P_{\Psi_{\bar{Z}}} A_r) \end{aligned}$$

\square

Theorem 11. *The possible measurement results of the α_r -measurement are exactly the eigenvalues of the associated operator A_r . The subspace E_i^r representing the outcome event labeled by α_i^r is the eigenspace pertaining to eigenvalue α_i^r . Accordingly, (124) constitutes the spectral decomposition of A_r .*

Proof. First, let $\psi \in E_i^r$. Then, due to (99), $A_r\psi = (\sum_{i=1}^{n_r} \alpha_i^r E_i^r)\psi = \alpha_i^r\psi$. Meaning that every α_i^r is an eigenvalue of A_r . Now consider an arbitrary eigenvector of A_r , that is, a vector $\psi \in H$ such that

$$A_r\psi = x\psi \quad (125)$$

with some $x \in \mathbb{R}$. Due to (99)–(100), $\{E_1^r, E_2^r, \dots, E_{n_r}^r\}$ constitutes an orthogonal decomposition of H , meaning that arbitrary $\psi \in H$ can be decomposed as

$$\psi = \sum_{i=1}^{n_r} \psi_i \quad \psi_i \in E_i^r$$

From (124) we have

$$\sum_{i=1}^{n_r} \alpha_i^r \psi_i = \sum_{i=1}^{n_r} x \psi_i \quad (126)$$

About the labeling we have assumed that $\alpha_i^r \neq \alpha_j^r$ for $i \neq j$, therefore, (126) implies that

$$\begin{aligned} x &= \alpha_i^r && \text{for one } \alpha_i^r \\ \psi_j &= 0 && \text{for all } j \neq i \end{aligned}$$

that is, $\psi \in E_i^r$. Meaning that (124) is the spectral decomposition of A_r . \square

A consequence of Theorems 10 and 11 is that if $f : \mathbb{R} \rightarrow \mathbb{R}$ is an arbitrary injective function “re-labeling” the outcomes, then

$$\begin{aligned} \langle f(\alpha_r) \rangle_{\bar{Z}} &= \sum_{i=1}^{n_r} f(\alpha_i^r) \pi(X_i^r | a_r) = \sum_{i=1}^{n_r} f(\alpha_i^r) Z_i^r \simeq \sum_{i=1}^{n_r} f(\alpha_i^r) \text{tr}(P_{\Psi_{\bar{Z}}} E_i^r) \\ &= \text{tr} \left(P_{\Psi_{\bar{Z}}} \sum_{i=1}^{n_r} f(\alpha_i^r) E_i^r \right) = \text{tr}(P_{\Psi_{\bar{Z}}} f(A_r)) \end{aligned}$$

7 Representation of Dynamics

Notice that not all unit vectors of H are involved in the representation of states. In order to specify the ones being involved, consider the following subspace $\mathcal{H} \subset H$:

$$\mathcal{H} = \text{span} \{ \Psi_{\vartheta} \}_{\vartheta \in \Theta}$$

where $\{ \Psi_{\vartheta} \}_{\vartheta \in \Theta}$ is the set of vectors in the direct sum (109), understood as being pairwise orthogonal, unit-length elements of H . Denote by \mathcal{O} the closed first hyperoctant (orthant) of the $(|\Theta| - 1)$ -dimensional sphere of unit vectors in \mathcal{H} :

$$\mathcal{O} = \left\{ \sum_{\vartheta \in \Theta} o_{\vartheta} \Psi_{\vartheta} \mid o_{\vartheta} \geq 0 \quad \sum_{\vartheta \in \Theta} o_{\vartheta}^2 = 1 \right\}$$

Obviously, there is a continuous one-to-one map between the Λ and \mathcal{O} :

$$O : \Lambda \rightarrow \mathcal{O}; \quad O(\vec{\lambda}) = \sum_{\vartheta \in \Theta} \sqrt{\lambda_{\vartheta}} \Psi_{\vartheta}$$

As we have shown, however, the states of the system actually are represented on the $\dim(\varphi(M, S))$ -dimensional slice $\Lambda_{\sigma} \subset \Lambda$ (see (80)). Accordingly, the quantum mechanical representation of states constitutes a $\dim(\varphi(M, S))$ -dimensional submanifold with boundary: $\mathcal{O}_{\sigma} = O(\Lambda_{\sigma}) \subset \mathcal{O}$.

Consequently, the time evolution of state $\vec{Z}(t)$ will be represented by a path in \mathcal{O}_{σ} :

$$\Psi(t) = O \circ \sigma(\vec{Z}(t))$$

The representation is of course not unique, as it depends on the choice of cross section σ . This is however inessential; just like a choice of a coordinate system.

If **(E4)** holds, that is the time evolution $\vec{Z}(t)$ can be generated by a one-parameter group of transformations on $\varphi(M, S)$, $\vec{Z}(t) = F_{t-t_0}(\vec{Z}(t_0))$, then the same is true for \mathcal{O}_{σ} . Let $G_t = O \circ \sigma \circ F_t \circ D \circ O^{-1}$. Obviously, G_t is a map $\mathcal{O}_{\sigma} \rightarrow \mathcal{O}_{\sigma}$, such that

$$G_t : \mathcal{O}_{\sigma} \rightarrow \mathcal{O}_{\sigma} \text{ is one-to-one}$$

$$G : \mathbb{R} \times \mathcal{O}_{\sigma} \rightarrow \mathcal{O}_{\sigma}; \quad (t, \Psi) \mapsto G_t(\Psi) \text{ is continuous}$$

$$G_{t+s} = G_s \circ G_t$$

$$G_{-t} = G_t^{-1}; \text{ consequently, } G_0 = id_{\mathcal{O}_{\sigma}}$$

and the time evolution of an arbitrary initial state $\Psi(t_0) \in \mathcal{O}_{\sigma}$ is $\Psi(t) = G_{t-t_0}(\Psi(t_0))$.

8 Questionable and Unquestionable in Quantum Mechanics

What we have *proved* in the above theorems, that is, statements (Q1)–(Q8), are nothing but the basic postulates of quantum theory. This means that the basic postulates of quantum theory are in fact analytic statements: they do not tell us anything about a physical system beyond the fact that the system can be described in empirical/operational terms—even if this logical relationship is not so evident. In this sense, of course, these postulates of quantum theory are unquestionable. Though, as we have seen, the Hilbert space quantum mechanical formalism is only an optional mathematical representation of the probabilistic behavior of a system—empirical facts do not necessitate this choice.

Nevertheless, it must be mentioned that the quantum-mechanics-like representation, characterized by (Q1)–(Q8), is not completely identical with standard quantum mechanics. There are several subtle deviations:

- (D1) There is no one-to-one correspondence between operationally meaningful physical quantities and self-adjoint operators. First of all, it is not necessarily true that every self-adjoint operator represents some operationally meaningful quantity.
- (D2) There is no obvious connection between commutation of the associated self-adjoint operators and joint measurability of the corresponding physical quantities. In general, there is no obvious role of the mathematically definable algebraic structures over the self-adjoint operators in the operational context. First of all because those mathematically “natural” structures are mostly meaningless in an operational sense. As we have already mentioned, the outcome *events* are ontologically prior to the labeling of the outcomes by means of numbers; and the events themselves are well represented in the subspace/projector lattice, prior to any self-adjoint operator associated with a numerical coordination.

For example, consider three real-valued physical quantities with labelings $\alpha_{r_1}, \alpha_{r_2}, \alpha_{r_3}$. The three physical quantities reflect three different features of the system defined by three different measurement operations. A functional relationship $\alpha_{r_1} = f(\alpha_{r_2}, \alpha_{r_3})$ means that whenever we perform the measurements $a_{r_1}, a_{r_2}, a_{r_3}$ in conjunction (meaning that $\{r_1, r_2, r_3\} \in \mathfrak{P}$) the outcomes $X_{i_1}^{r_1}, X_{i_2}^{r_2}, X_{i_3}^{r_3}$ are strongly correlated: if $X_{i_2}^{r_2}$ and $X_{i_3}^{r_3}$ are the outcomes of a_{r_2} and a_{r_3} , labeled by $\alpha_{i_2}^{r_2}$ and $\alpha_{i_3}^{r_3}$, then the outcome of measurement a_{r_1} , $X_{i_1}^{r_1}$, is the one labeled by $\alpha_{i_1}^{r_1} = f(\alpha_{i_2}^{r_2}, \alpha_{i_3}^{r_3})$. That is, in probabilistic terms:

$$\begin{aligned} & \pi(\alpha_{r_1}^{-1}(f(\alpha_{i_2}^{r_2}, \alpha_{i_3}^{r_3}))) \wedge \alpha_{r_2}^{-1}(\alpha_{i_2}^{r_2}) \wedge \alpha_{r_3}^{-1}(\alpha_{i_3}^{r_3}) | a_{r_1} \wedge a_{r_2} \wedge a_{r_3} \\ & = \pi(\alpha_{r_2}^{-1}(\alpha_{i_2}^{r_2}) \wedge \alpha_{r_3}^{-1}(\alpha_{i_3}^{r_3}) | a_{r_1} \wedge a_{r_2} \wedge a_{r_3}) \end{aligned} \quad (127)$$

This contingent fact of regularity in the observed relative frequencies of physical events is what is a part of the ontology. And it is well reflected in our quantum mechanical representation, in spite of the fact that the relationship (127) is generally not reflected in some algebraic or other functional relation of the associated self-adjoint operators A_{r_1} , A_{r_2} and A_{r_3} .

- (D3) It is worthwhile emphasizing that the Hilbert space of representation is finite dimensional and real. It is of course no problem to embed the whole representation into a complex Hilbert space of the same dimension. As it follows from (99) and (103), the required minimal dimension increases with increasing the number of possible measurements m , and/or increasing the number of possible outcomes n_r . In any event, it is finite until we have a finite operational setup. Employing complex Hilbert spaces is only necessary if, in addition to the stipulated operational setup, we have some further algebraic requirements, for example, in the form of commutation relations, and the likes. How those further requirements are justified in operational terms, of course, can be a question.

- (D4) There is no problem with the empirical meaning of the lattice-theoretic meet of subspaces/projectors representing outcome events: the meet represents the empirically meaningful conjunction of the outcome events, regardless whether the corresponding projectors commute or not. Of course, by definition (17), the conjunctions that do not belong to S have zero probability in all states of the system.

In contrast, the lattice-theoretic joins and orthocomplements, in general, have nothing to do with the disjunctions and negations of the outcome events. Nevertheless, as we have seen, the quantum state uniquely determines the probabilities on the whole event algebra, including the conjunctions, disjunctions and negations of all events—in the sense of Theorem 1.

- (D5) All possible states of the system, $\vec{Z} \in \varphi(M, S)$, are represented by *pure* states. That is to say, the quantum mechanical notion of mixed state is not needed. The reason is very simple. $\varphi(M, S)$ is a convex polytope being closed under convex linear combinations. The state of the system intended to be represented by a mixed state, say,

$$W = \mu_1 P_{\Psi_{\vec{z}_1}} + \mu_2 P_{\Psi_{\vec{z}_2}} \quad \mu_1, \mu_2 \geq 0; \quad \mu_1 + \mu_2 = 1$$

is nothing but another element of $\varphi(M, S)$,

$$\vec{Z}_3 = \mu_1 \vec{Z}_1 + \mu_2 \vec{Z}_2 \in \varphi(M, S)$$

However, in our representation theorem (Theorem 9) the Hilbert space and the representations of the outcome events are constructed in a way that all states $\vec{Z} \in \varphi(M, S)$ are represented by a suitable state vector in one and the same Hilbert space. Therefore, \vec{Z}_3 is also represented by a pure state $P_{\Psi_{\vec{z}_3}}$ with a suitably constructed state vector $\Psi_{\vec{z}_3}$. Namely, given that

$$\begin{aligned} \vec{Z}_1 &= \sum_{\vartheta \in \Theta} \lambda_{\vartheta}^1 \vec{w}_{\vartheta} \quad \lambda_{\vartheta}^1 \geq 0, \quad \sum_{\vartheta \in \Theta} \lambda_{\vartheta}^1 = 1 \\ \vec{Z}_2 &= \sum_{\vartheta \in \Theta} \lambda_{\vartheta}^2 \vec{w}_{\vartheta} \quad \lambda_{\vartheta}^2 \geq 0, \quad \sum_{\vartheta \in \Theta} \lambda_{\vartheta}^2 = 1 \end{aligned}$$

we have

$$\vec{Z}_3 = \sum_{\vartheta \in \Theta} (\mu_1 \lambda_{\vartheta}^1 + \mu_2 \lambda_{\vartheta}^2) \vec{w}_{\vartheta}$$

therefore, from (109),

$$\Psi_{\vec{z}_3} = \bigoplus_{\vartheta \in \Theta} \sqrt{\mu_1 \lambda_{\vartheta}^1 + \mu_2 \lambda_{\vartheta}^2} \Psi_{\vartheta}$$

To avoid a possible misunderstanding, it is worthwhile mentioning that all we said above is not in contradiction with the mathematical fact that the

density operators W and $P_{\Psi_{z_3}}$ generate different “quantum probability” measures over the *whole* subspace lattice $L(H)$. The two measures will coincide on those elements of $L(H)$ that represent operationally meaningful events— $E_i^r, E_{i_1}^{r_1} \wedge \dots \wedge E_{i_L}^{r_L}$ for $i \in I^M, r_1 \dots r_L \in S$. This reinforces the point in (D4) that there is no one-to-one correspondence between the operationally meaningful events and the elements of $L(H)$.

- (D6) We don’t need to invoke the entire Hilbert space for representing the totality of operationally meaningful possible states of the system; subspace \mathcal{H} is sufficient. Even in this restricted sense, there is no one-to-one correspondence between the rays of the subspace $\mathcal{H} \subset H$ and the states of the system. The unit vectors involved in the representation are the ones pointing to \mathcal{O}_σ , a $\dim(\varphi(M, S))$ -dimensional submanifold with boundary on the unit sphere of \mathcal{H} .
- (D7) The so called “superposition principle” does not hold. The ray determined by the linear combination of two different vectors pointing to \mathcal{O}_σ does not necessarily intersect \mathcal{O}_σ ; meaning that such a linear combination, in general, has nothing to do with a third state of the system. Neither has it anything to do with the logical/probability theoretic notion of “disjunction” of events, of course. Nevertheless, as we have already emphasized in (D4) and (D5), all possible states of the system are well represented in \mathcal{O}_σ ; and these states uniquely determine the probabilities on the whole event algebra of operationally meaningful events, including their disjunctions too.
- (D8) The dynamics of the system can be well represented in the usual way, by means of G_t , a one-parameter group of transformations of the state manifold \mathcal{O}_σ . These transformations are in no way related to the unitary transformations of H (or \mathcal{H}); because they do not respect the linear structure of the Hilbert space or orthogonality; but they do respect that the state space \mathcal{O}_σ is a manifold with boundary.

It is remarkable that most of the above mentioned deviations from the quantum mechanical folklore are related with exactly those issues in the foundations of quantum mechanics that have been hotly debated for long decades (e.g. Strauss 1936; Reichenbach 1944; Popper 1967; Park and Margenau 1968; 1971; Ross 1974; Bell 1987; Gudder 1988; Malament 1992; Leggett 1998; Griffiths 2013; Cassinelli and Lahti 2017; Fröhlich and Pizzo 2022). The fact that so much of the core of quantum theory can be unquestionably deduced from three elementary empirical conditions, equally true about all physical systems whether classical or quantum, may shed new light on these old problems in the foundations.

Appendix

Theorem 12. Let P be a polytope in \mathbb{R}^d , defined by the following set of linear inequalities:

$$\langle \vec{\omega}_\mu, \vec{f} \rangle - b_\mu \leq 0 \quad \text{for all } \mu \in I \quad (128)$$

For each $\vec{f} \in P$, define the active index set:

$$I_{\vec{f}} := \{ \mu \in I \mid \langle \vec{\omega}_\mu, \vec{f} \rangle - b_\mu = 0 \}$$

$\vec{f} \in P$ is a vertex of P if and only if

$$\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}} = \mathbb{R}^d \quad (129)$$

Proof. First, suppose \vec{f} is vertex of P , but $\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}} \neq \mathbb{R}^d$. Then choose a non-zero $\vec{g} \in (\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}})^\perp$. Obviously, if $\mu \notin I_{\vec{f}}$ then there exists a neighborhood U of \vec{f} such that $\mu \notin I_{\vec{f}_*}$ for all $\vec{f}_* \in U$. Consider the points $\vec{f} + \lambda \vec{g}$. If λ is small enough, both $\vec{f} + \lambda \vec{g}$ and $\vec{f} - \lambda \vec{g}$ are in P , since (128) are satisfied. Now, we can write

$$\vec{f} = \frac{1}{2} \left((\vec{f} + \lambda \vec{g}) + (\vec{f} - \lambda \vec{g}) \right)$$

which contradicts the fact that \vec{f} is vertex of P .

Second, now suppose that $\vec{f} \in P$ and $\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}} = \mathbb{R}^d$. Suppose $\vec{f} = \lambda \vec{f}_* + (1 - \lambda) \vec{f}_{**}$ with some $\vec{f}_*, \vec{f}_{**} \in P$ and $0 < \lambda < 1$. We know that $\mu \in I_{\vec{f}}$ implies

$$\langle \vec{\omega}_\mu, \vec{f} \rangle = \lambda \langle \vec{\omega}_\mu, \vec{f}_* \rangle + (1 - \lambda) \langle \vec{\omega}_\mu, \vec{f}_{**} \rangle = b_\mu$$

On the other hand, from (128) we have

$$\begin{aligned} \langle \vec{\omega}_\mu, \vec{f}_* \rangle &\leq b_\mu \\ \langle \vec{\omega}_\mu, \vec{f}_{**} \rangle &\leq b_\mu \end{aligned}$$

which implies that $\langle \vec{\omega}_\mu, \vec{f} \rangle = \langle \vec{\omega}_\mu, \vec{f}_* \rangle = \langle \vec{\omega}_\mu, \vec{f}_{**} \rangle$ (for all $\mu \in I_{\vec{f}}$). Therefore,

$$\left(\vec{f} - \vec{f}_* \right), \left(\vec{f} - \vec{f}_{**} \right) \in \left(\text{span} \{ \vec{\omega}_\mu \}_{\mu \in I_{\vec{f}}} \right)^\perp = \emptyset$$

meaning that $\vec{f} = \vec{f}_* = \vec{f}_{**}$. Therefore, \vec{f} is a vertex. \square

Funding

This work was supported by Hungarian National Research, Development and Innovation Office (Grant No. K134275).

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